

# Commonsense Reasoning in Natural Language Processing

CPSC 532V

Lecture 11: Multimodal Commonsense

Instructor: Vered Shwartz

Presented by:

Sahithya Ravi: sahiravi@cs.ubc.ca,

Aditya Chinchure : aditya10@cs.ubc.ca

# Outline

## Reasoning about vision and language

- Motivation
- Visual Commonsense Reasoning tasks
- Vision and language representations and models
- Open problems and future directions



# Outline

## Reasoning about vision and language

- **Motivation**
- Visual Commonsense Reasoning tasks
- Vision and language representations and models
- Open problems and future directions

# Can you learn meaning only from text?

A monkey grabbed a plastic bag and jumped out the window of a moving bus.

# Can you learn meaning only from text?

A monkey grabbed a plastic bag and jumped out the window of a moving bus.

💭 **Why did the monkey grab the bag?**

(Stealing food? Curious?)

💭 **How did it look while jumping?**

(Was it frantic, playful, or scared?)

💭 **What was inside the bag?**

(Food?)

💭 **What were the humans in the scene doing?**

(Chasing it? Ignoring it?)

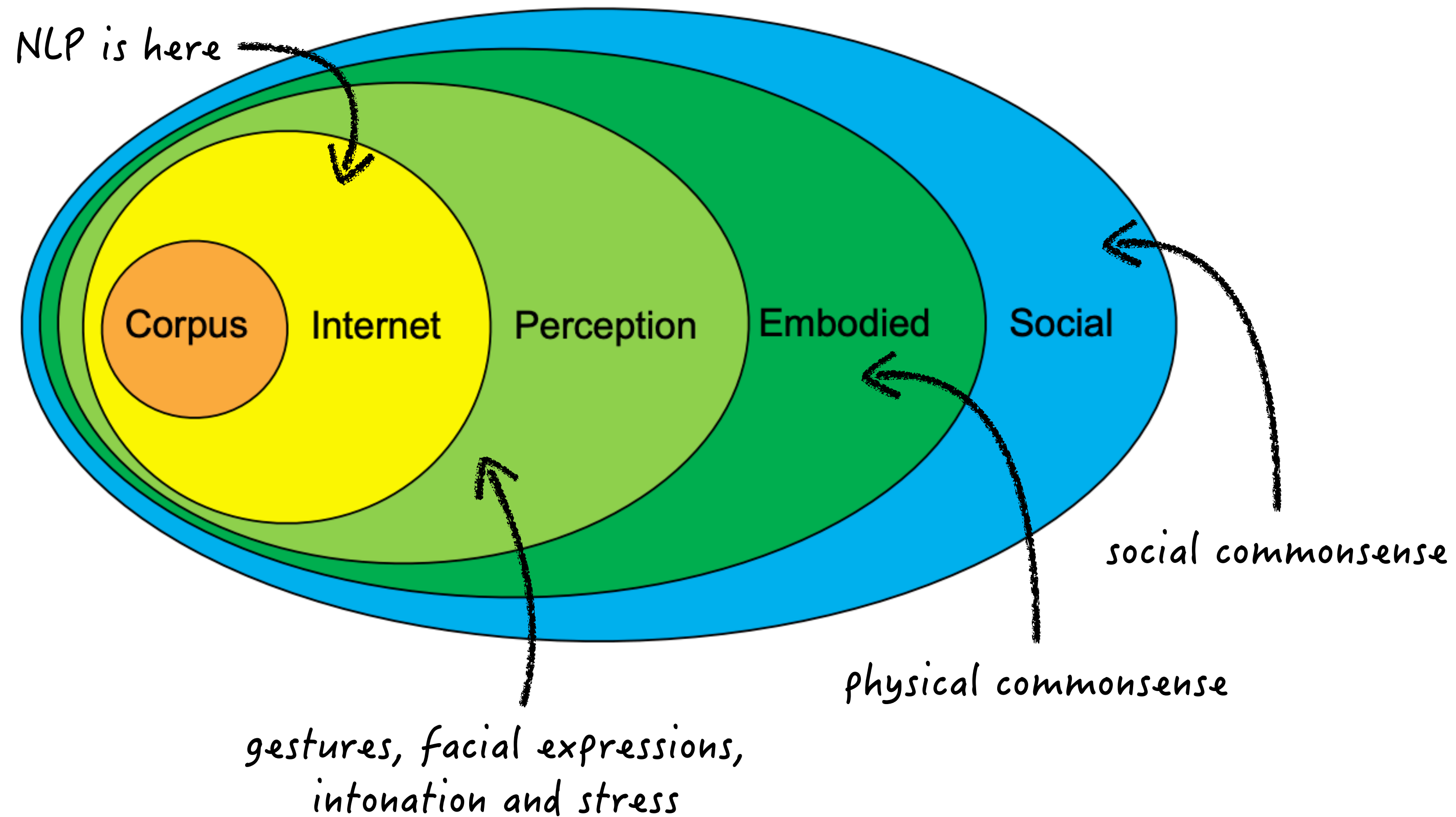
# Can you learn meaning only from text?

A monkey grabbed a plastic bag and jumped out the window of a moving bus.



- 💭 **Why did the monkey grab the bag?**
- 💭 **How did it look while jumping?**
- 💭 **What was inside the bag?**
- 💭 **What were the humans in the scene doing?**

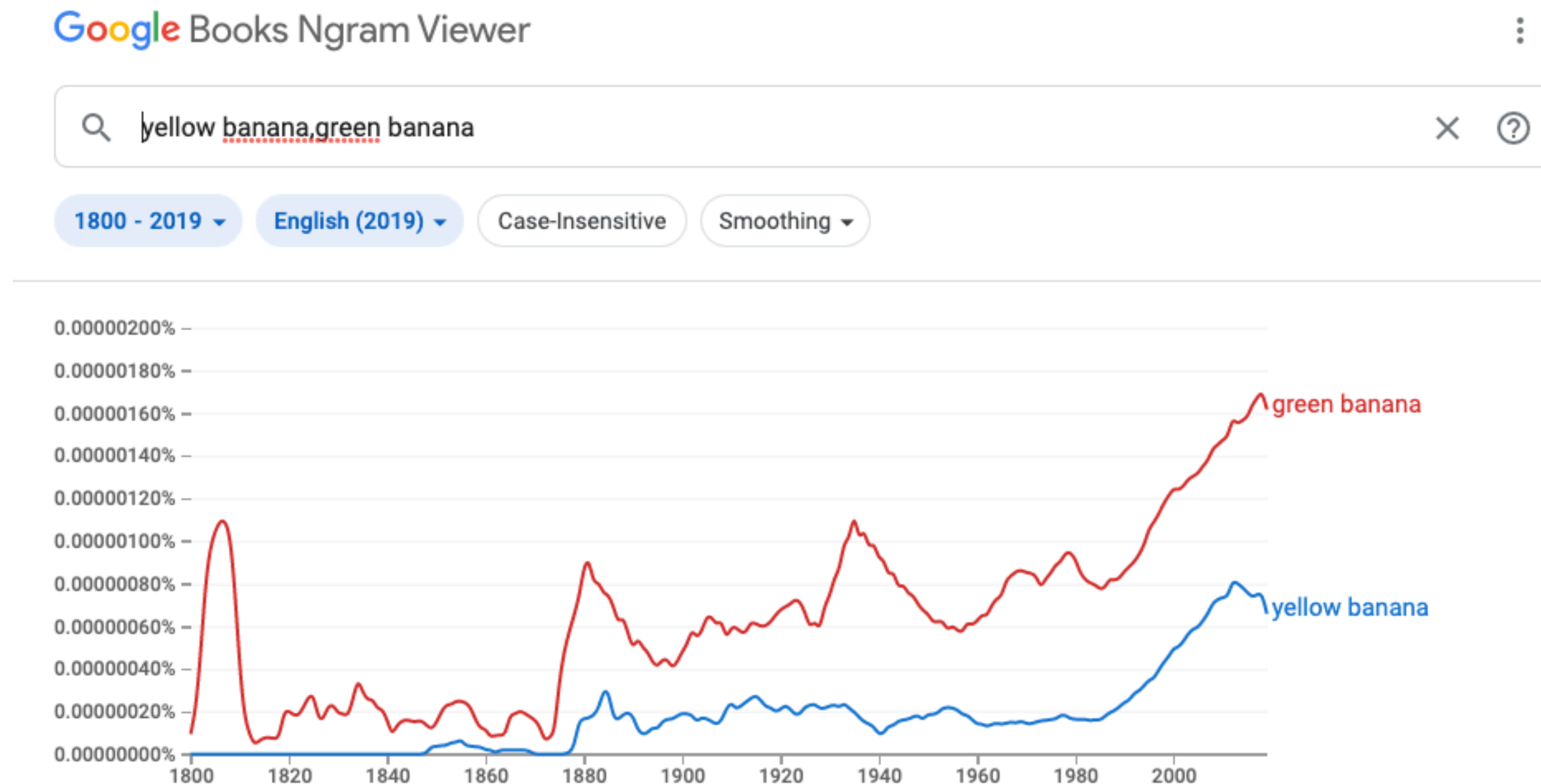
# Can you learn meaning only from text?





# What is the colour of a banana?

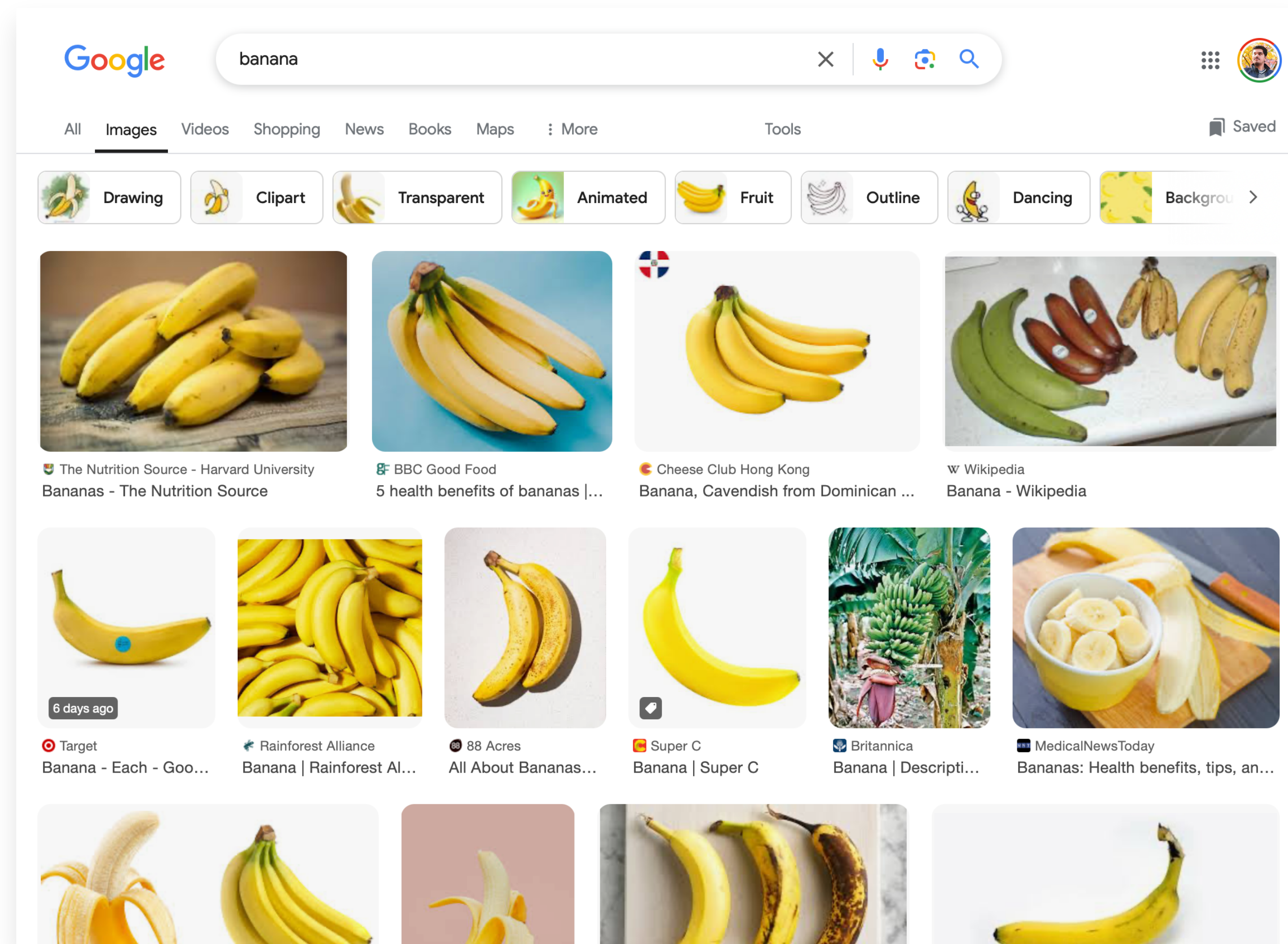
Text has a predominant occurrence of green bananas...



Reporting bias  
(Gordon and Van Durme, 2013)

# What is the colour of a banana?

Text has a predominant occurrence of green bananas... but not in images





# Acquiring Commonsense Knowledge

## Sources of Knowledge

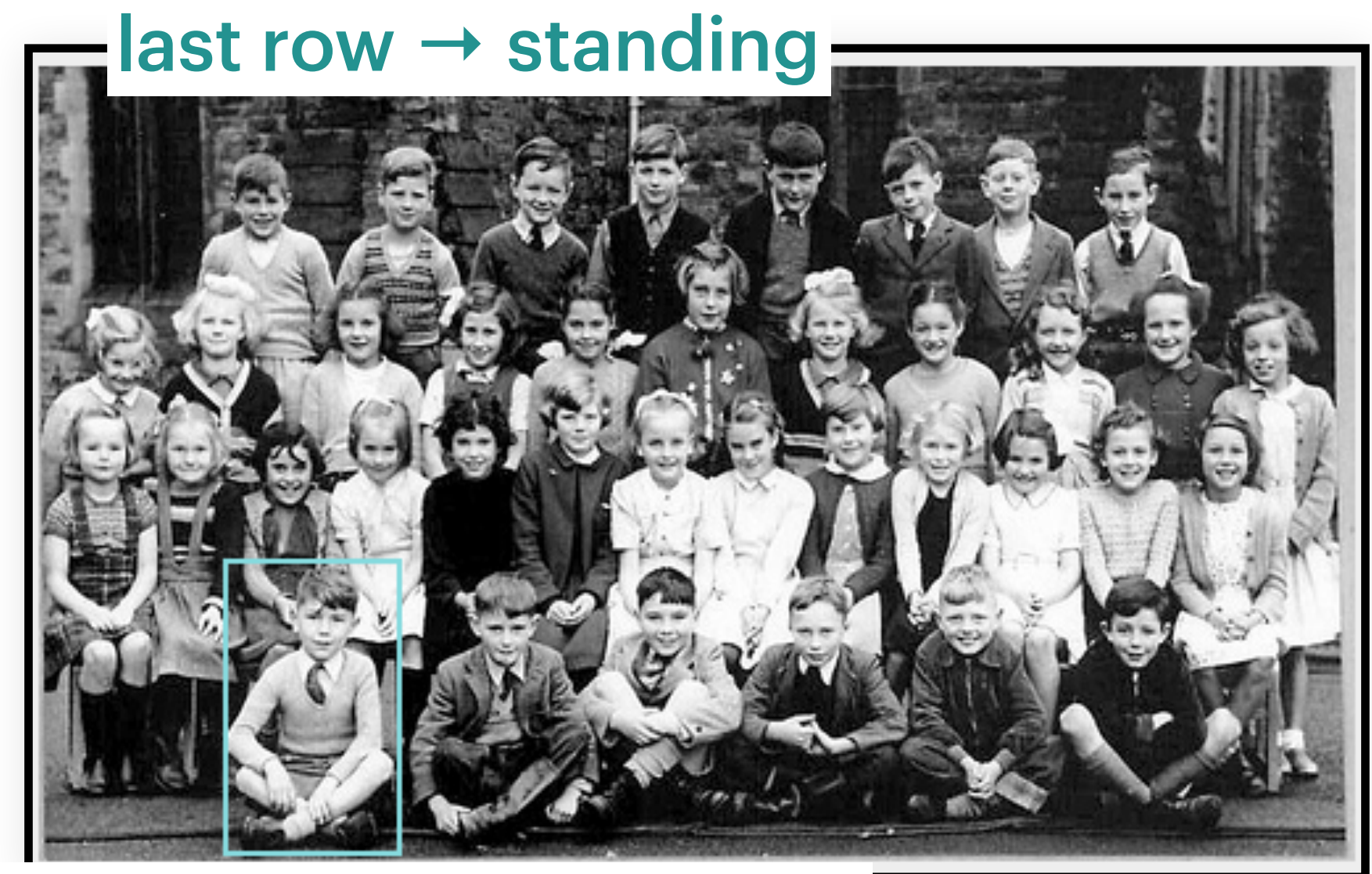
1 from language

2 from images

3 from video

4 from audio

Photograph of 6th grade  
students from the batch of 1995  
at ABC School...

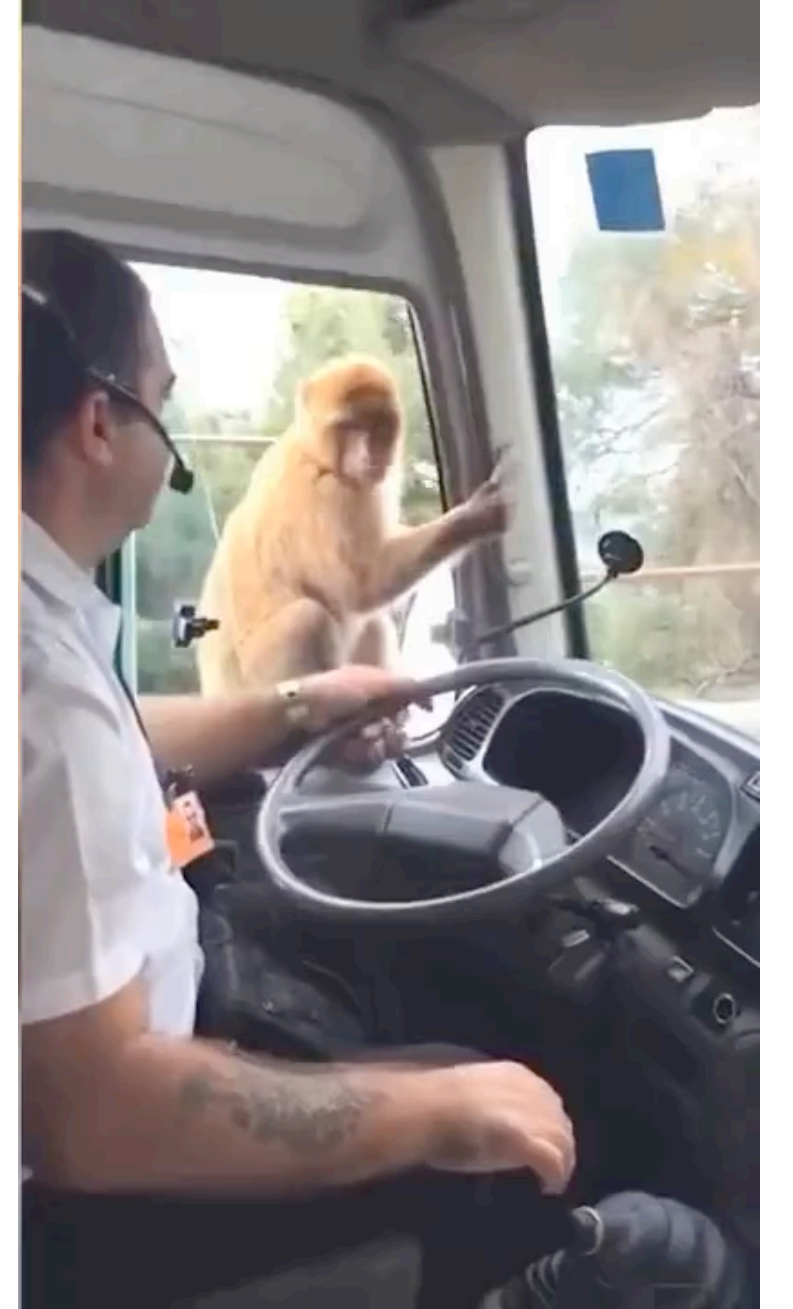


Multimodal Learning!



# Multimodal Model Skills?

- Perception - How many humans are there?
- Causal Reasoning – Why did the monkey jump?
- Temporal Understanding – What happened before and after?
- Physical Intuition – Could a monkey safely jump from a moving bus?
- Social & Commonsense Knowledge – Was the monkey stealing or playing?



**Multimodal Models need to see 🦋, interpret 💡, and reason 🤔**

# Outline

## Reasoning about vision and language

- Motivation
- **Visual Commonsense Reasoning tasks**
- Vision and language representations and models
- Open problems and future directions



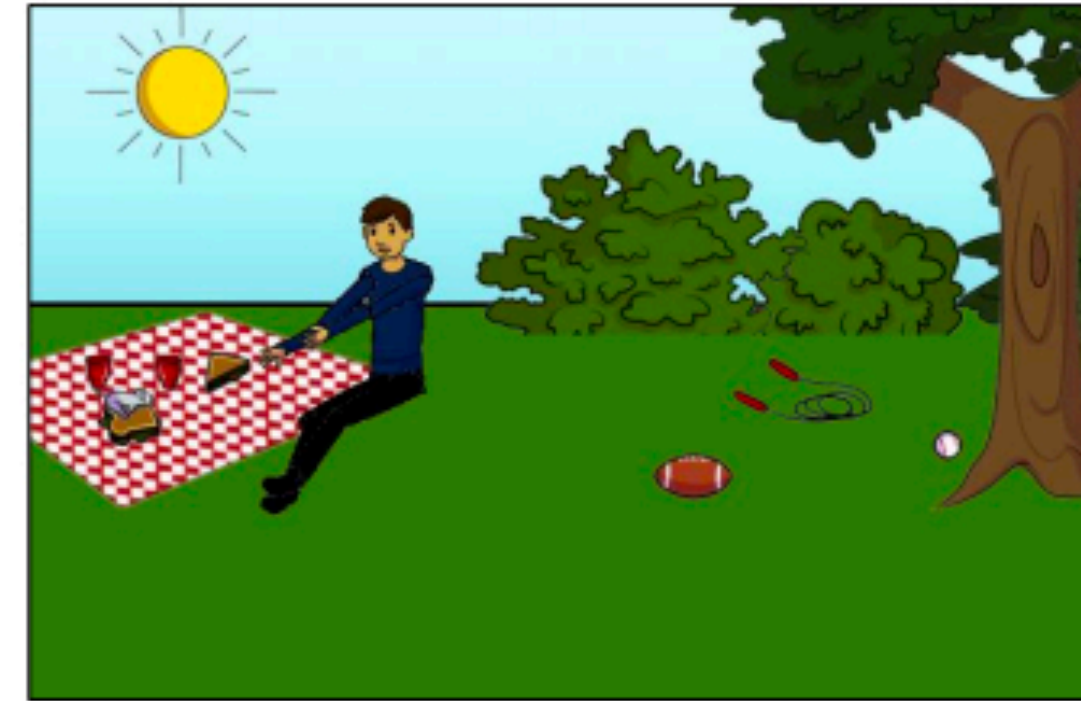
# Visual Question Answering



What color are her eyes?  
What is the mustache made of?



How many slices of pizza are there?  
Is this a vegetarian pizza?



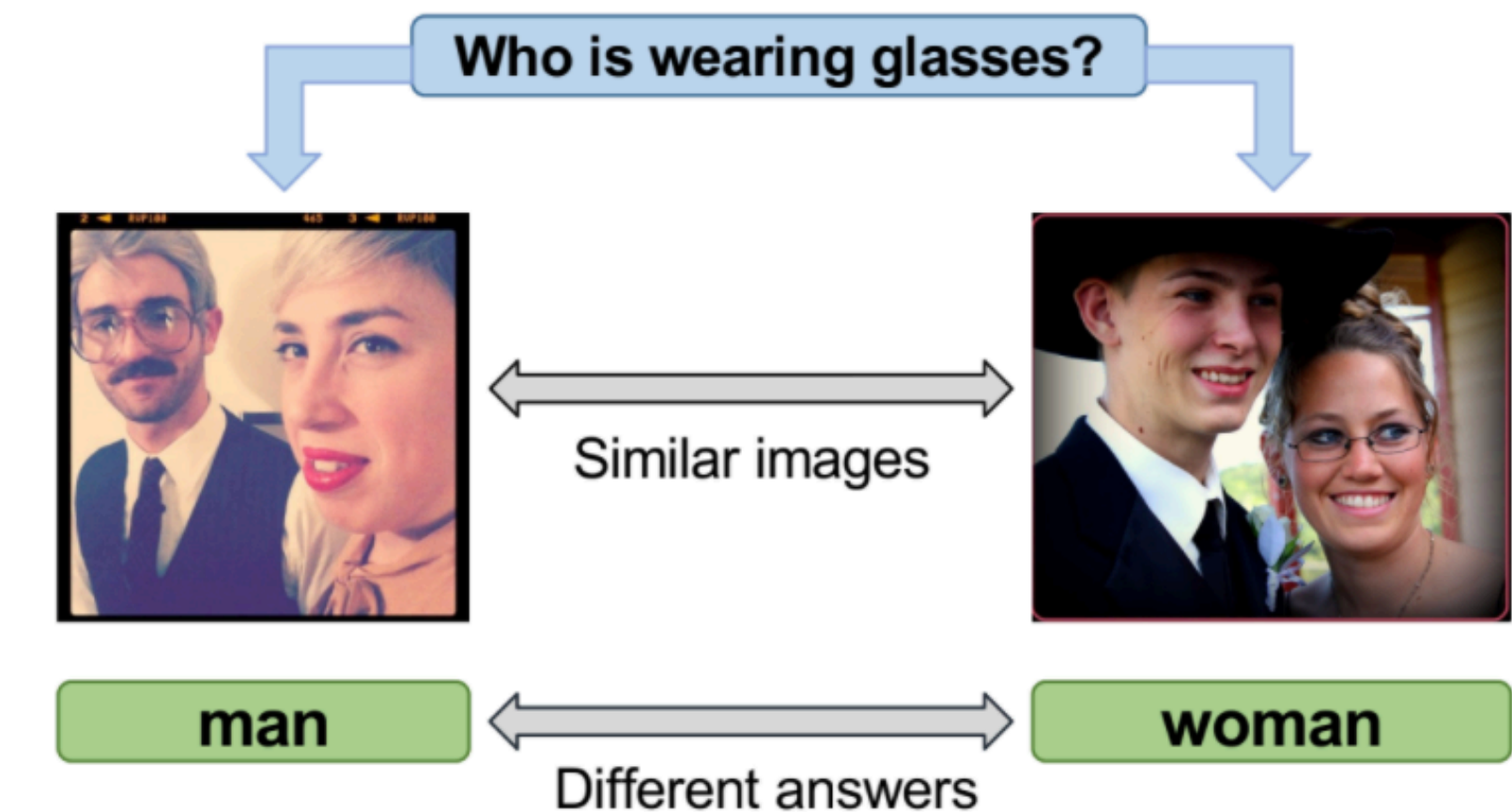
Is this person expecting company?  
What is just under the tree?



Does it appear to be rainy?  
Does this person have 20/20 vision?

- Open-ended questions about images.
- Require an understanding of vision, language and some commonsense.
- >200K images, >1M questions, >11M candidate answers
- The questions are mostly about **what is in the images**.
- Automatic evaluation

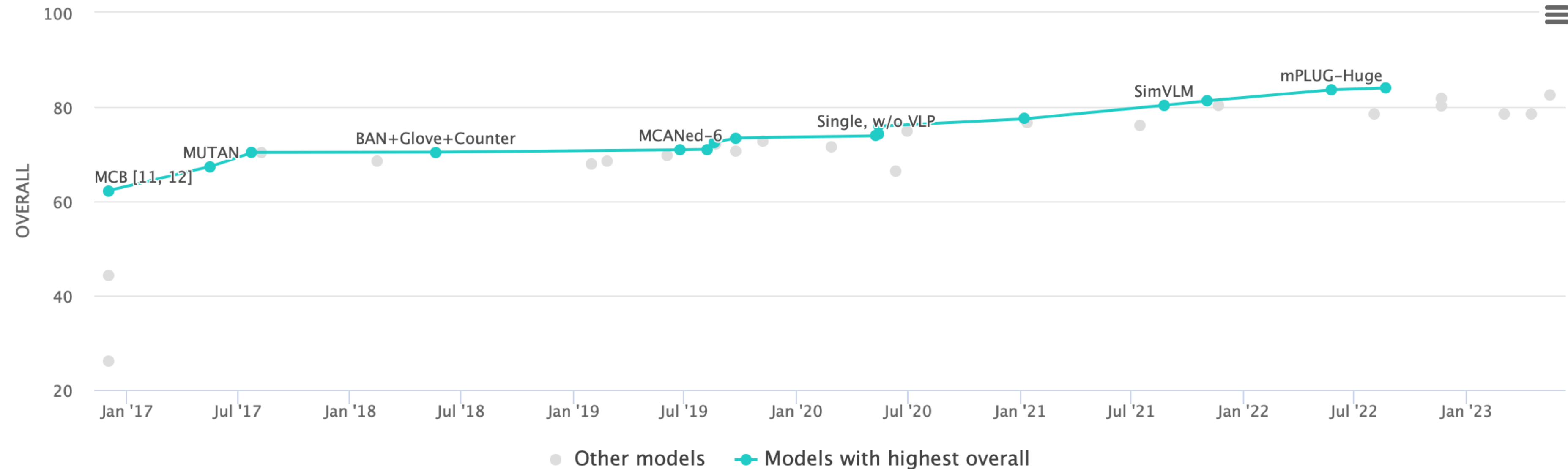
$$\text{Acc}(\textit{ans}) = \min \left\{ \frac{\# \text{humans that said } \textit{ans}}{3}, 1 \right\}$$





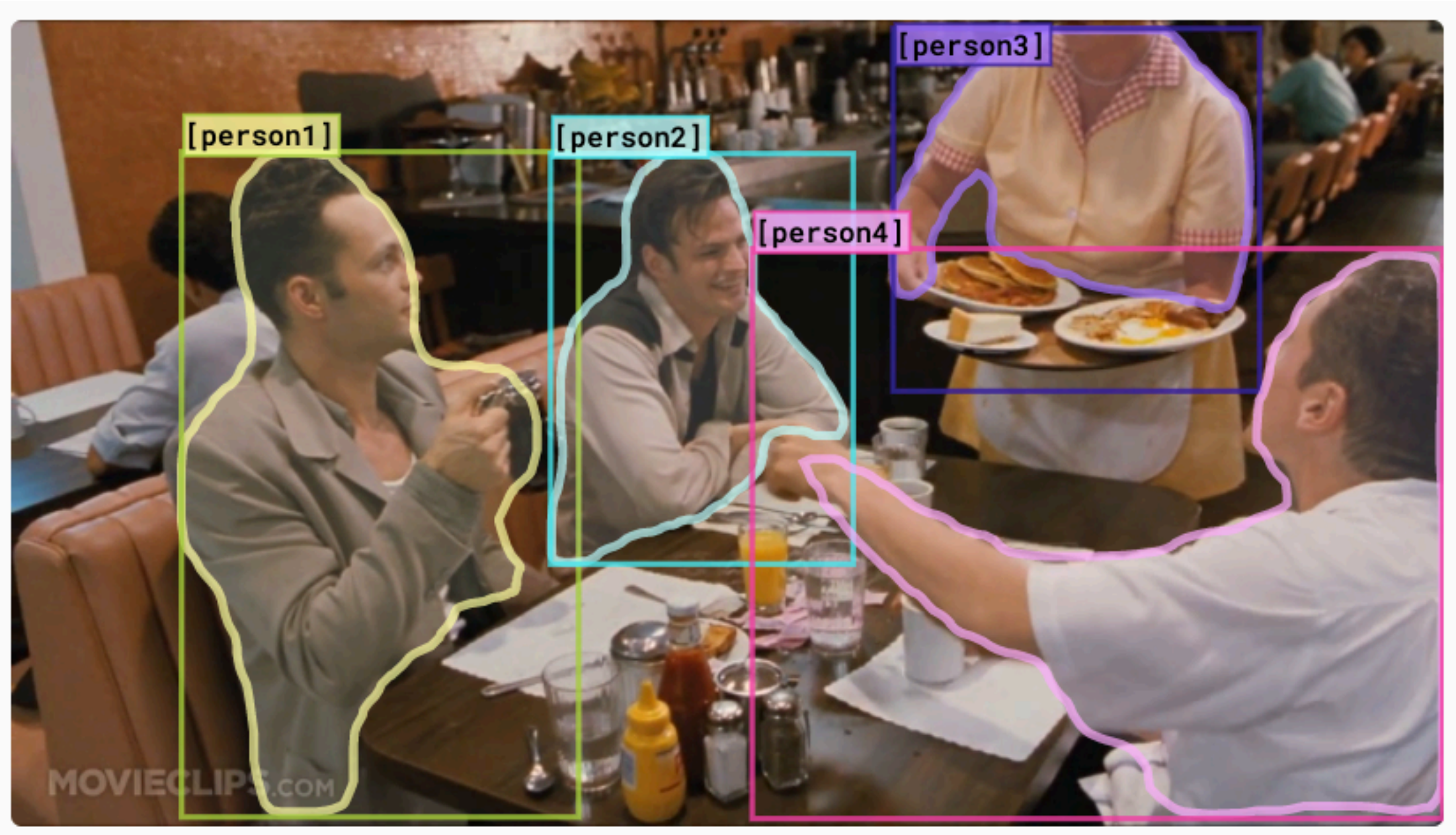
# Visual Question Answering

👁 Perception



Model performance is almost close to human performance!

# Visual Commonsense Reasoning



Why is [person4] pointing at [person1]?

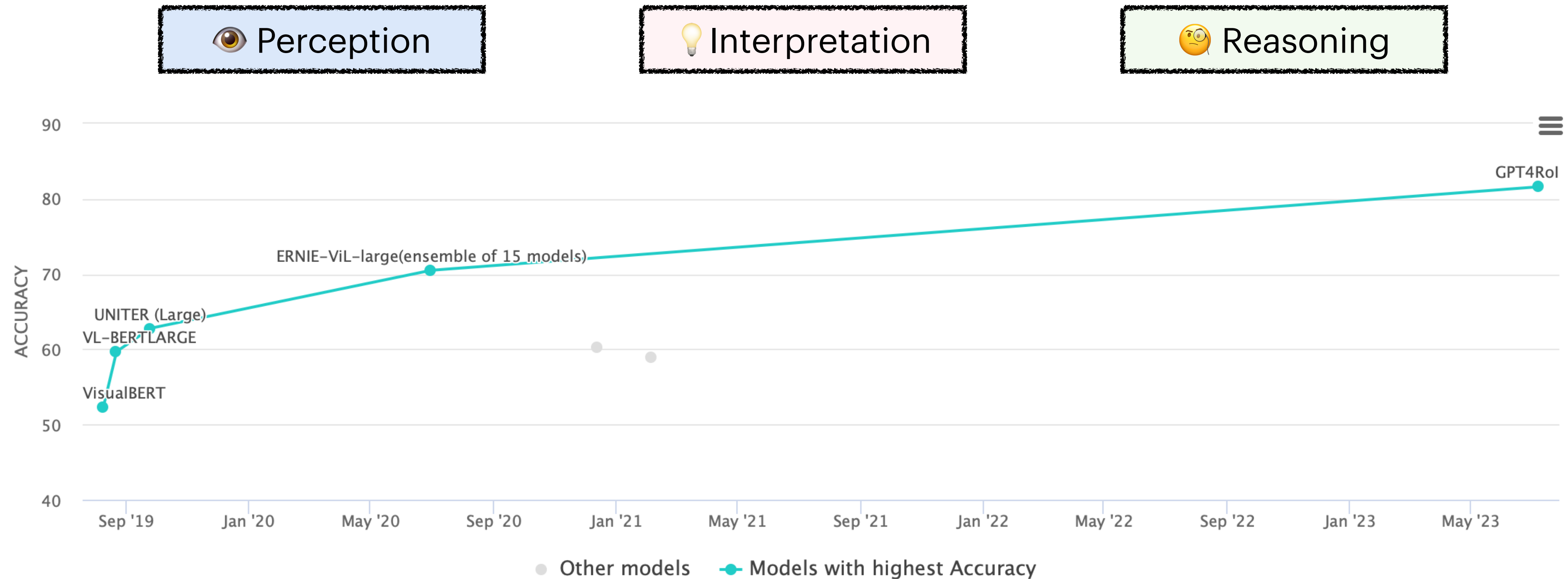
- a) He is telling [person3] that [person1] ordered the pancakes.
- b) He just told a joke.
- c) He is feeling accusatory towards [person1].
- d) He is giving [person1] directions.

Rationale: I think so because...

- a) [person1] has the pancakes in front of him.
- b) [person4] is taking everyone's order and asked for clarification.
- c) [person3] is looking at the pancakes both she and [person2] are smiling slightly.
- d) [person3] is delivering food to the table, and she might not know whose order is whose.



# Visual Commonsense Reasoning



Requires **RoI-based reasoning** to achieve human-level performance



# BLINK: “Seeing” vs “Perceiving”



Perception

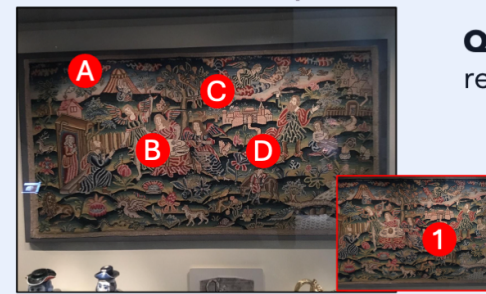


Interpretation



Reasoning

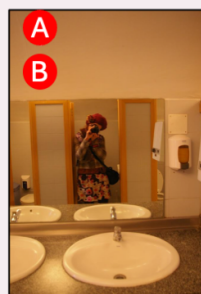
## Visual correspondence



Q: Which point corresponds to the reference point 1?

- (a) A (b) B  
(c) C (d) D

## Relative reflectance



Q: Consider the surface color (color without shading) of the two points in the image. Which one is darker, or the color is about the same?

- (a) A is darker (b) B is darker  
(c) About the same

## Counting

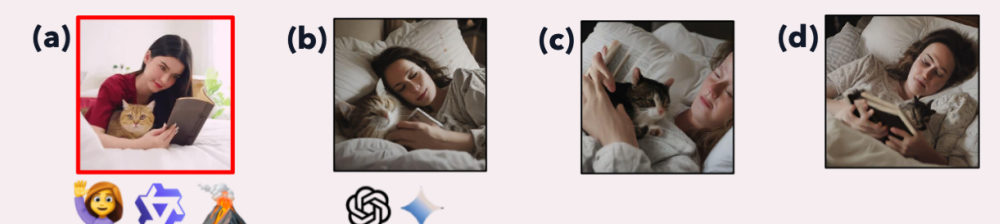


Q: How many fingers are in front of the bathtub?

- (a) 4 (b) 3  
(c) 2 (d) 5

## Forensics detection

Q: Which image is most likely to be a real photograph?



## Relative depth



Q: Which point is closer?

- (a) A (b) B

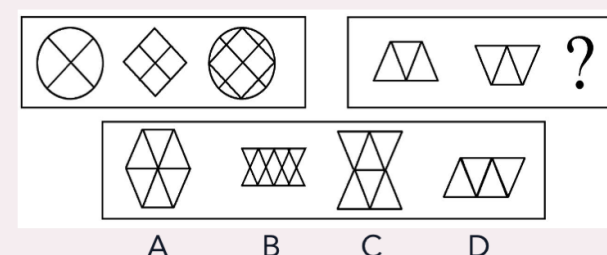
## Spatial reasoning



Q: Is the bed at the right side of the dining table?

- (a) Yes (b) No

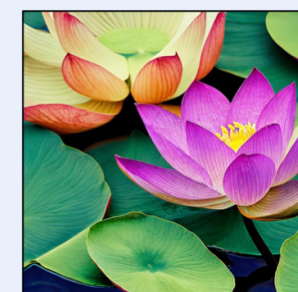
## IQ test



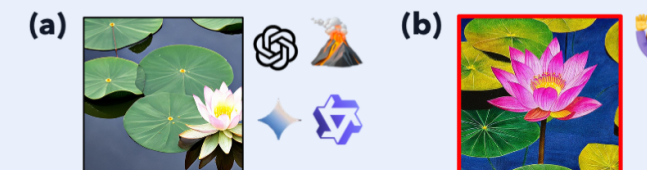
Q: Which image comes at the end?

- (a) A (b) B  
(c) C (d) D

## Visual similarity



Q: Which image is most similar to the reference image?



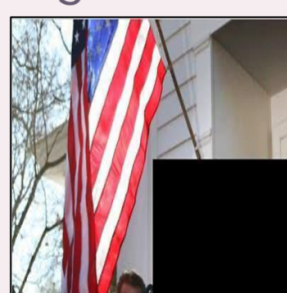
## Multi-view reasoning



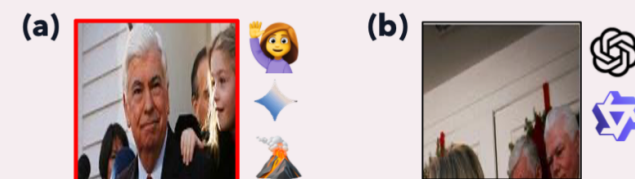
Q: The first image is from the beginning of the video and the second image is from the end. Is the camera moving towards left or right when shooting the video?

- (a) left (b) right

## Jigsaw



Q: Which image fits the missing part in the first image?



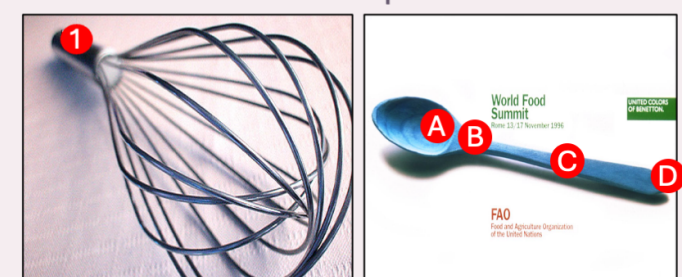
## Semantic correspondence



Q: Which point is semantically similar to the reference point 1?

- (a) A (b) B  
(c) C (d) D

## Functional correspondence



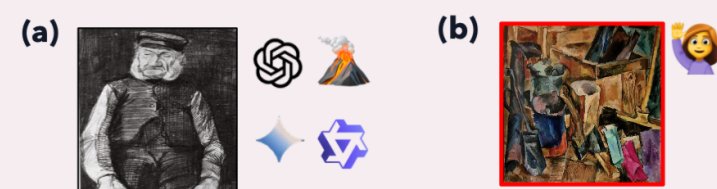
Q: Which point is functionally similar to the reference point 1 during mixing?

- (a) A (b) B  
(c) C (d) D

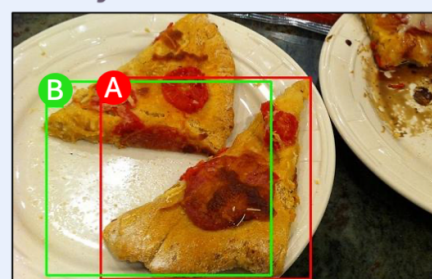
## Art style



Q: Which image fits the missing part in the first image?



## Object localization



Q: Which bounding box more accurately encloses the bun?

- (a) A (b) B



Ground Truth



Human



GTP4-V



Gemini Pro



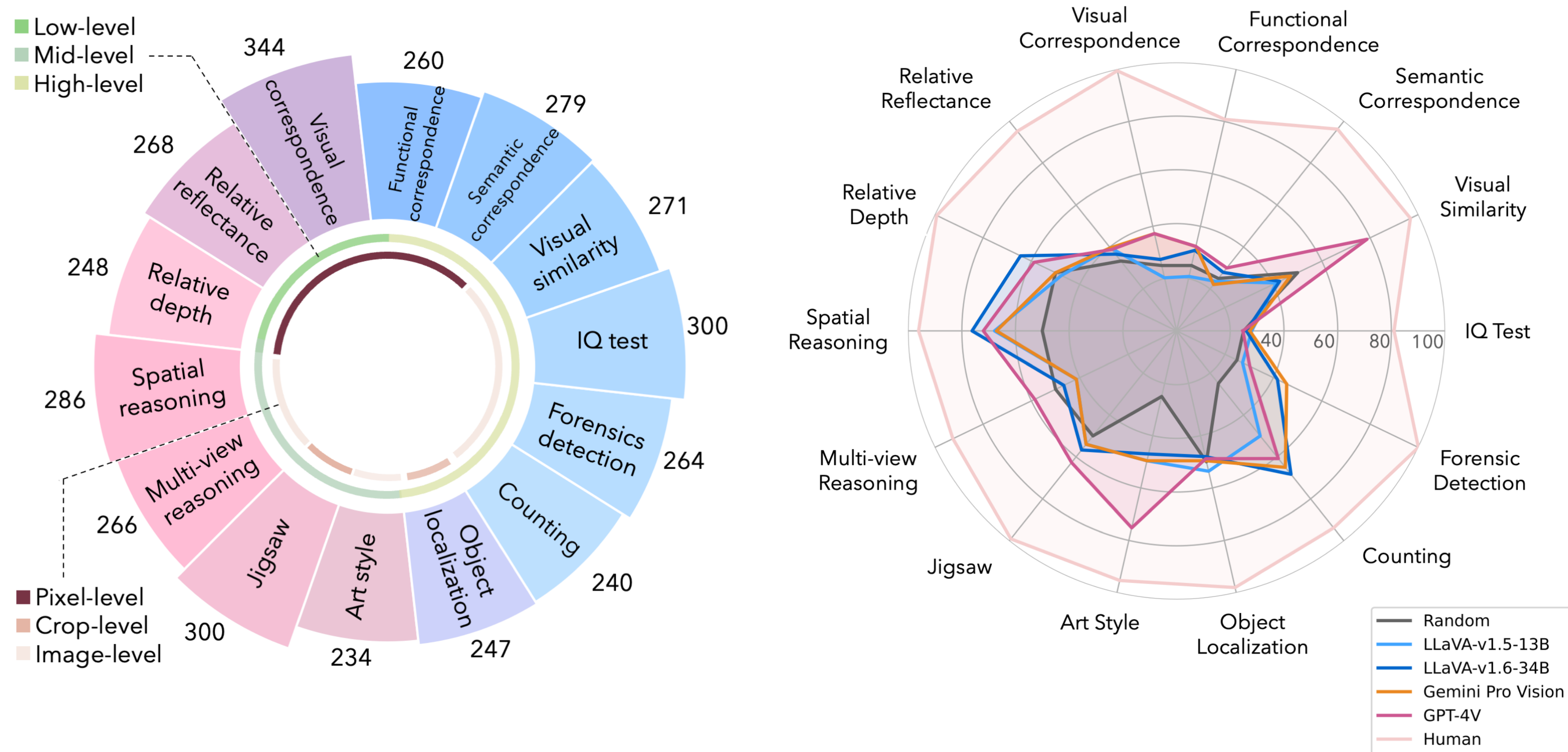
Qwen-VL-Max



LLaVA-34B



# BLINK: “Seeing” vs “Perceiving”



While these problems only takes human a "blink" to solve, they exceed the capabilities of current multimodal large language models with mean performance **35-42%**

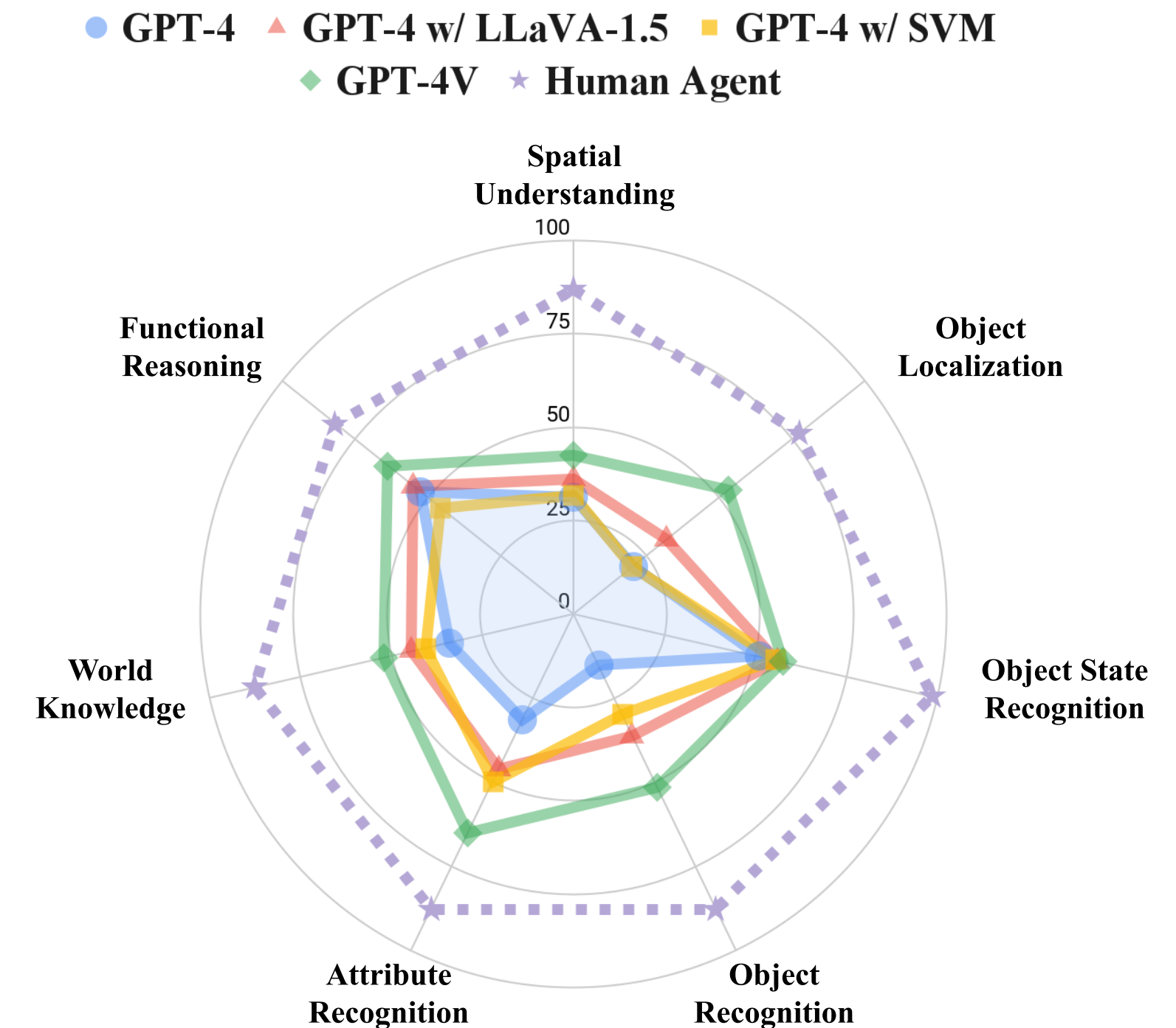
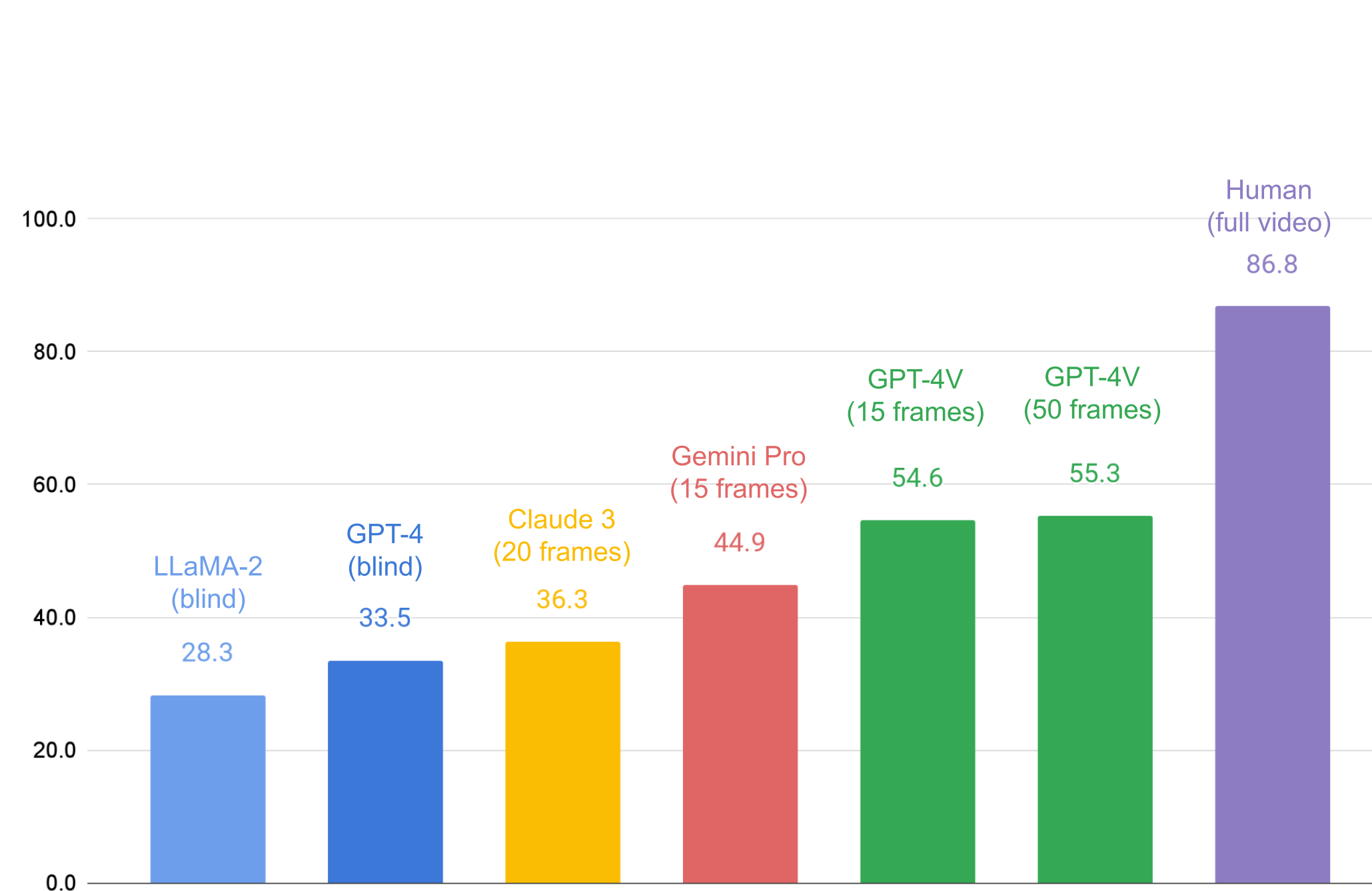


# OpenEQA: Embodied QA

## Video Understanding + Planning



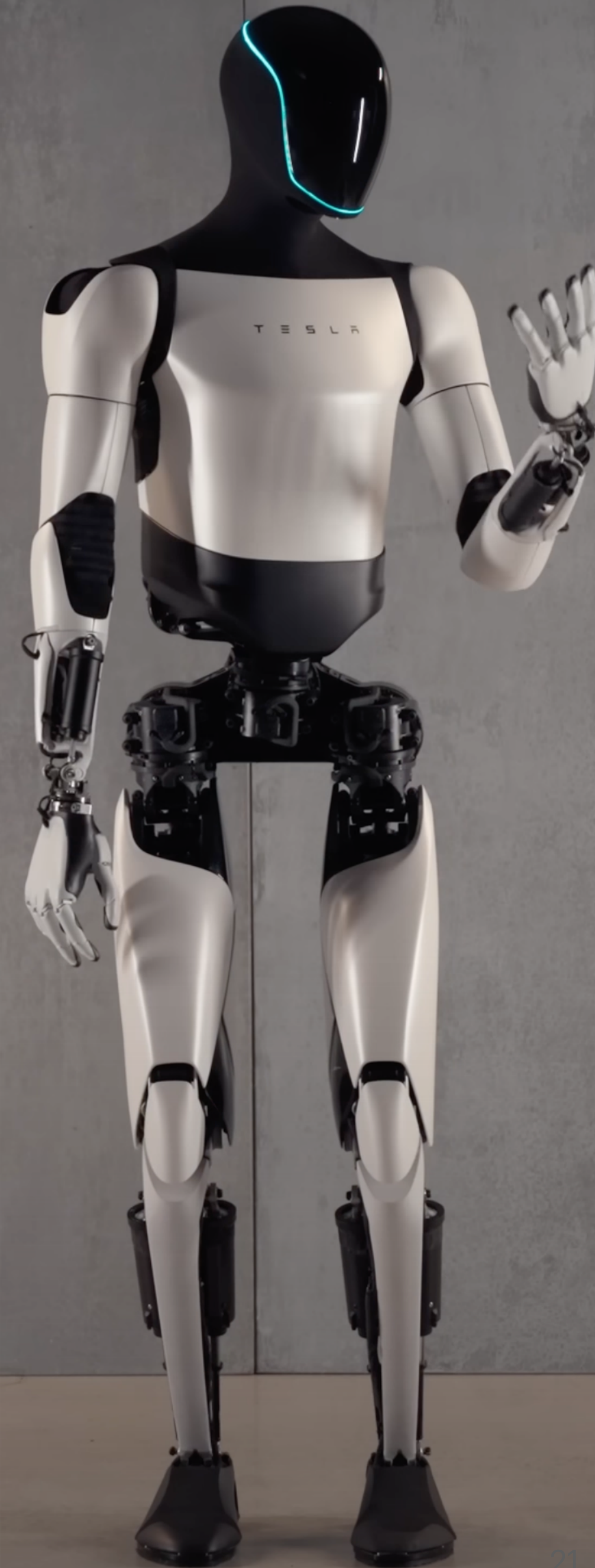
# Performance on OpenEQA



VLMs perform better than LLMs, but tasks that require **episodic memory** are still hard and substantially worse than human performance - these tasks require long form video understanding.

# From Word Models to World Models

- Large language models (LLMs), seem to have captured a **linguistic** understanding of the world.
- LLMs can answer all kinds of questions based on their knowledge, but they have no idea what is currently going on in the world around them.
- Enhancing LLMs with the ability to “see” the world and **situating** them in a user’s smart glasses or on a home robot
- Rather than simply predicting the next token in a string, an embodied AI agent would show that it’s grounded in an understanding of the physical world.





# Outline

## Reasoning about vision and language

- Motivation
- Visual Commonsense Reasoning tasks
- **Vision and language representations and models**
- Open problems and future directions

# Vision Transformer

**Images can be represented as tokens too!**

Sentence to word tokens:

"hi, I am a short sentence"



'hi' ',' 'I' 'am' 'a' 'short' 'sentence'

---

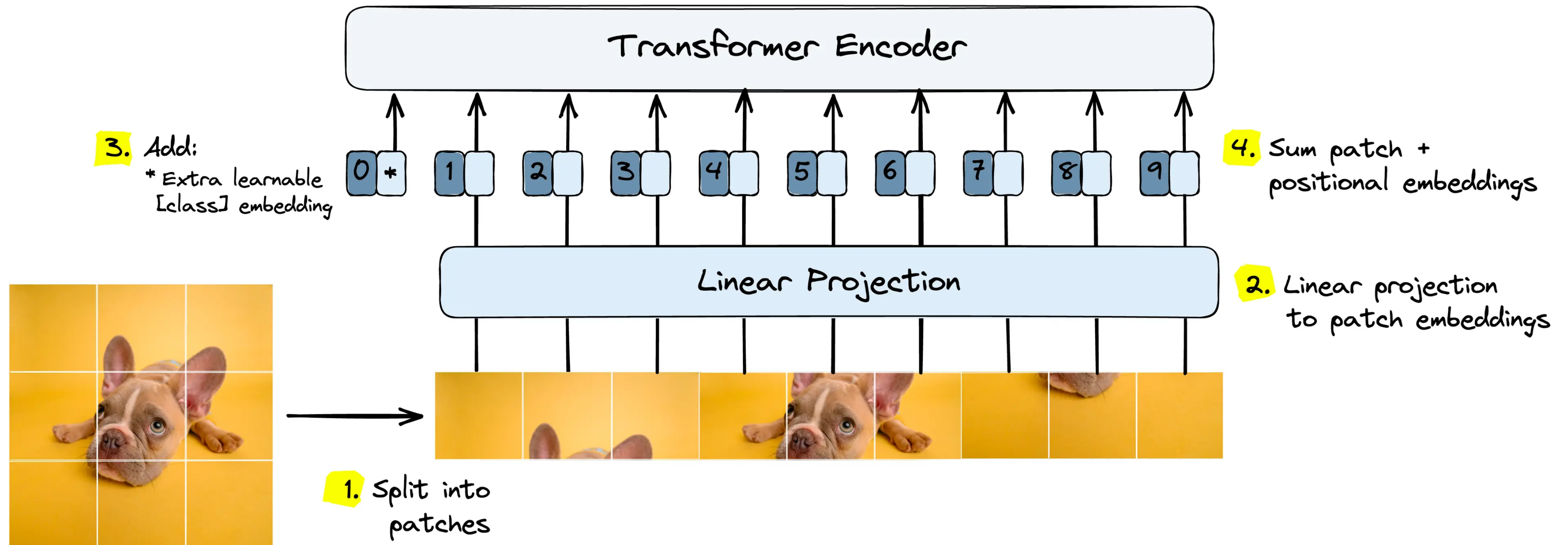
Image to image patches:



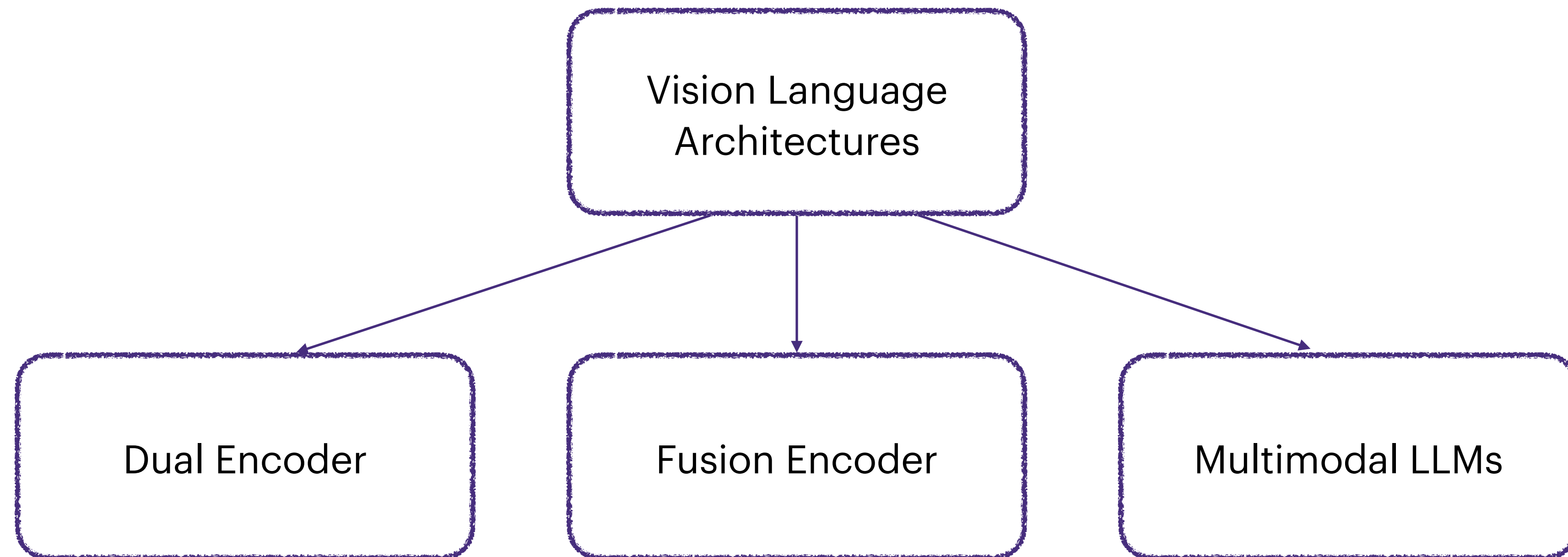
The input image (e.g.,  $224 \times 224$  pixels) is divided into small non-overlapping patches (e.g.,  $16 \times 16$  pixels each).

# Vision Transformer

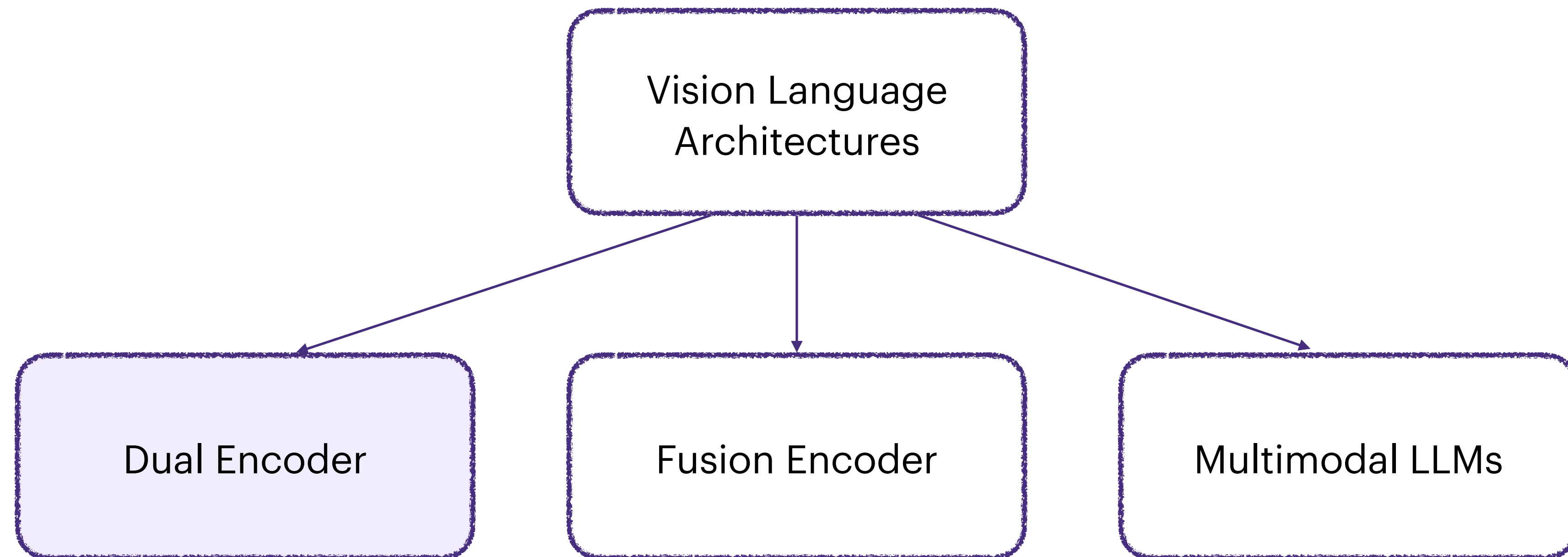
Images can be represented as tokens too!



# Vision Language Models



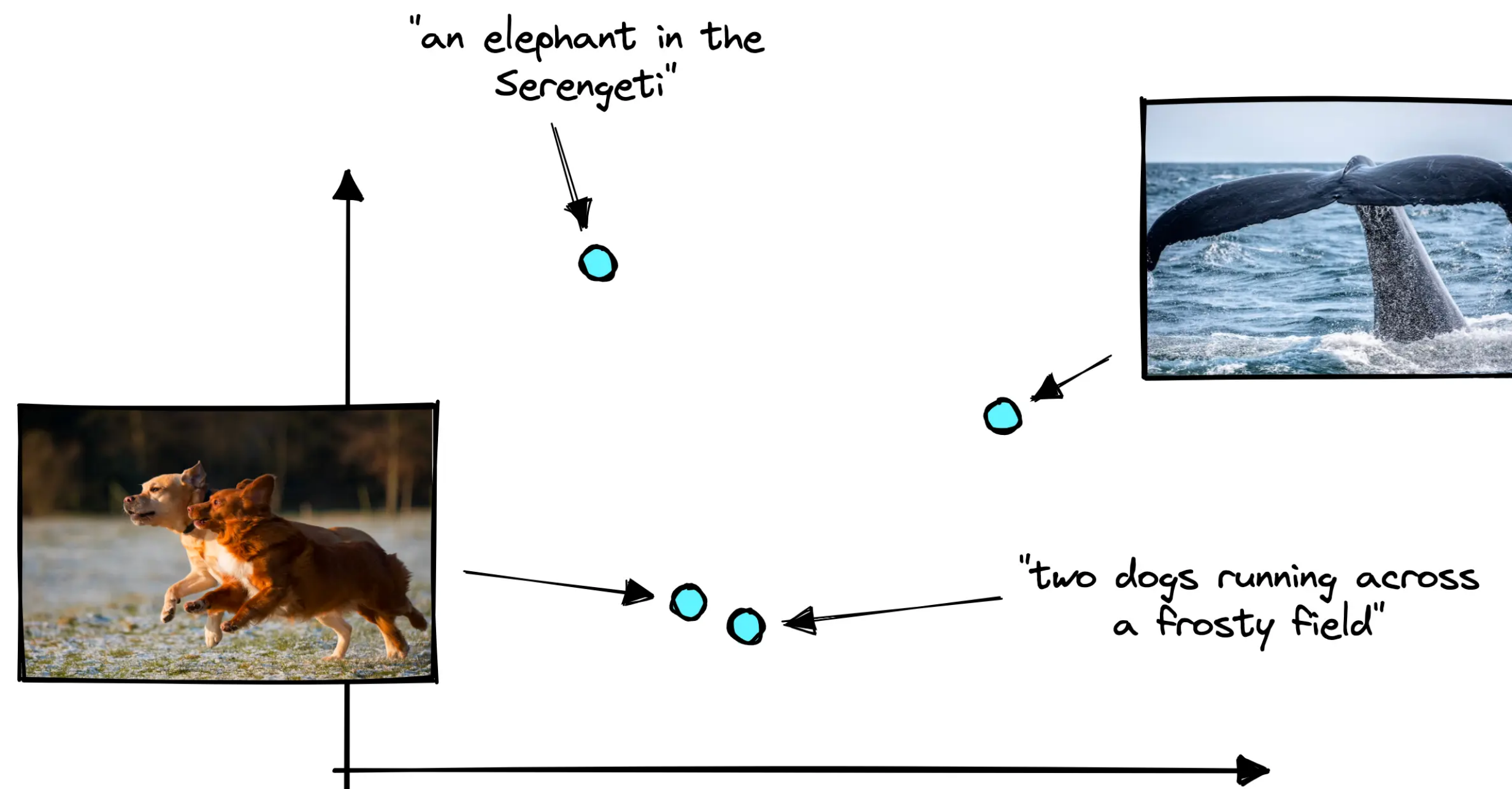
# Vision Language Models





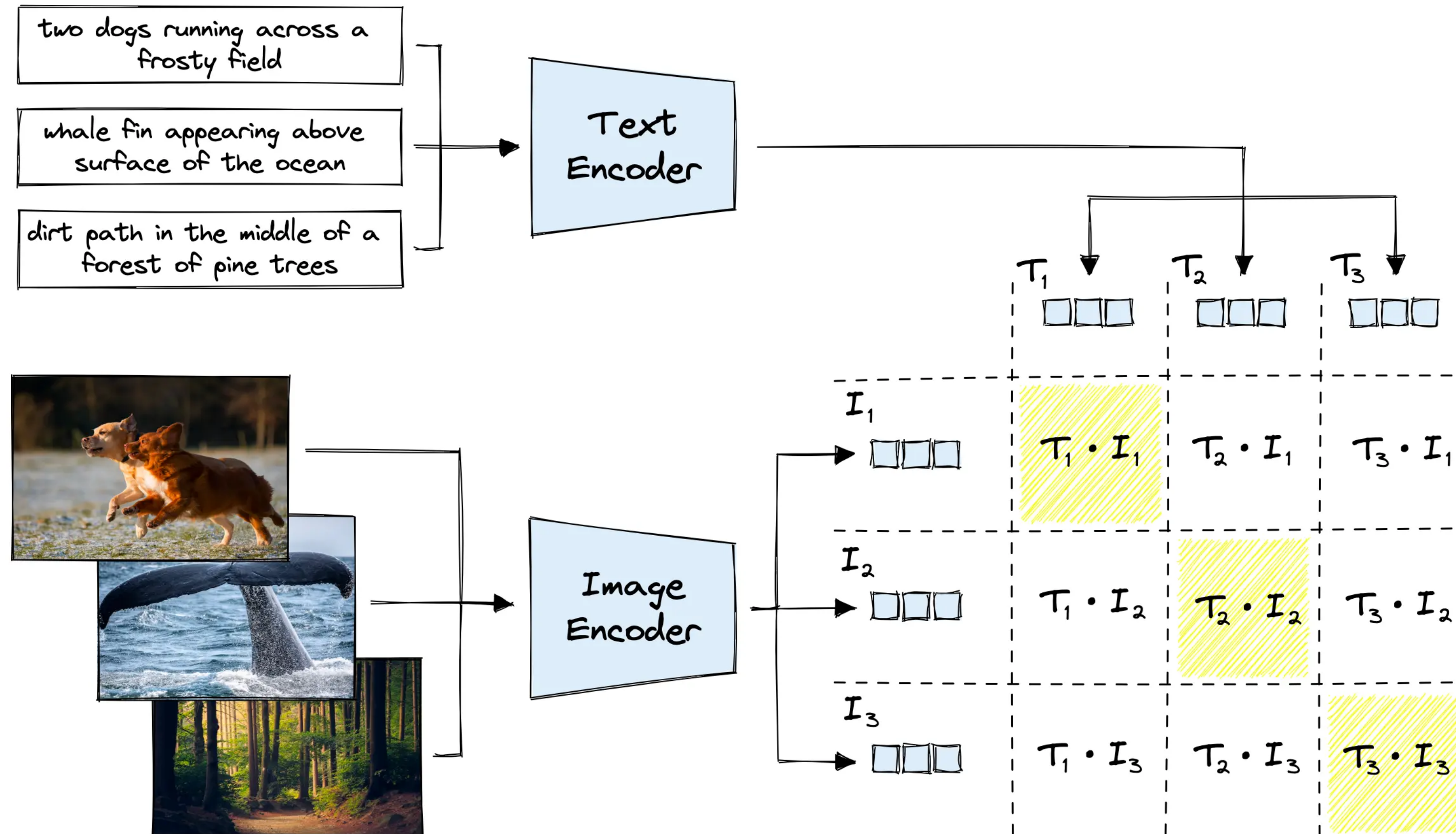
# CLIP

**Goal: Representing Images and Text in the same embedding space**



# CLIP

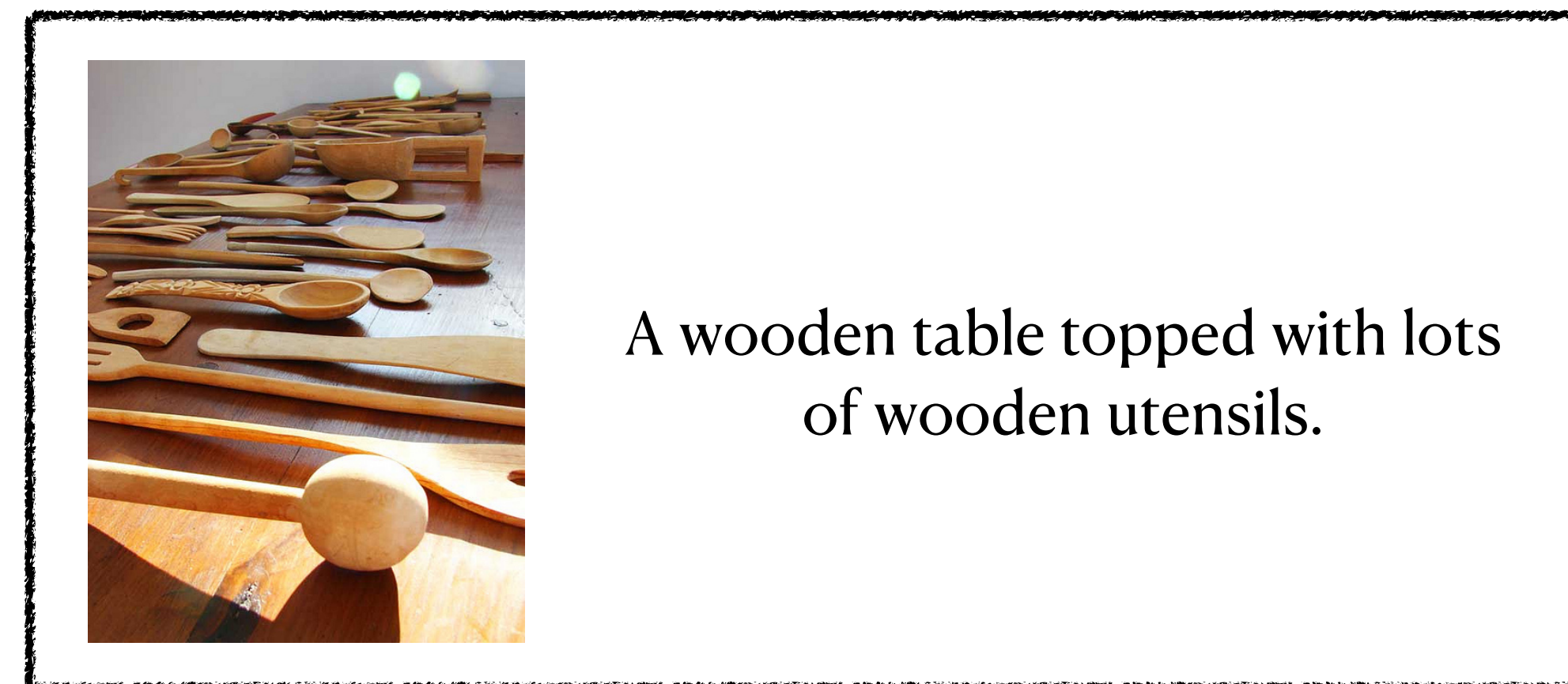
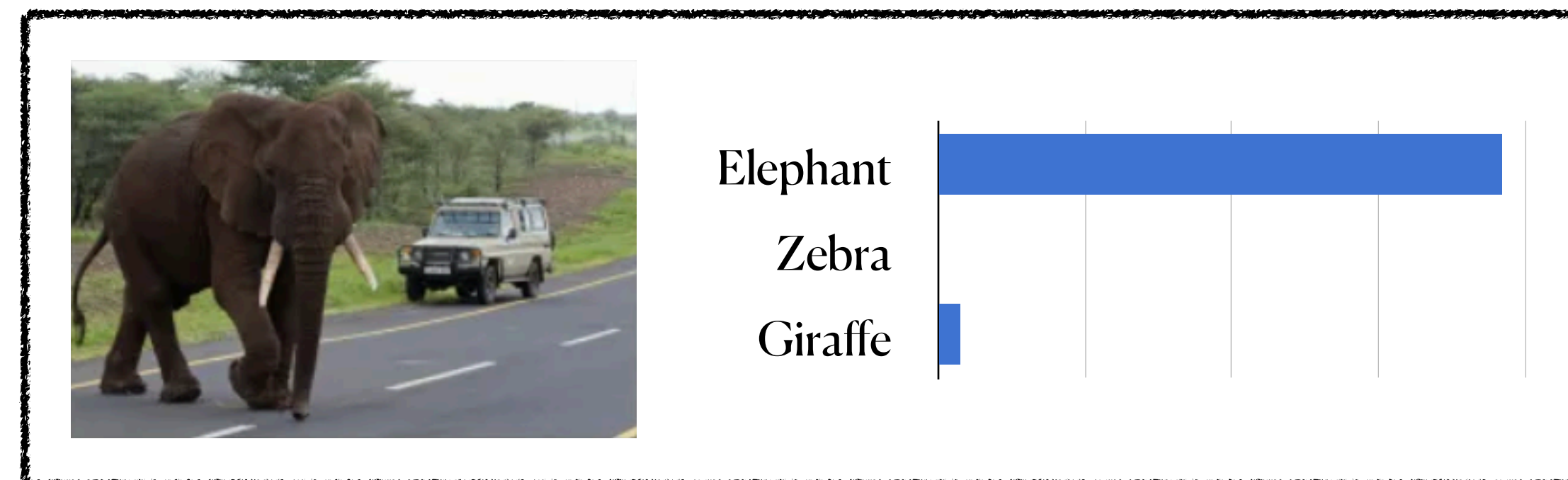
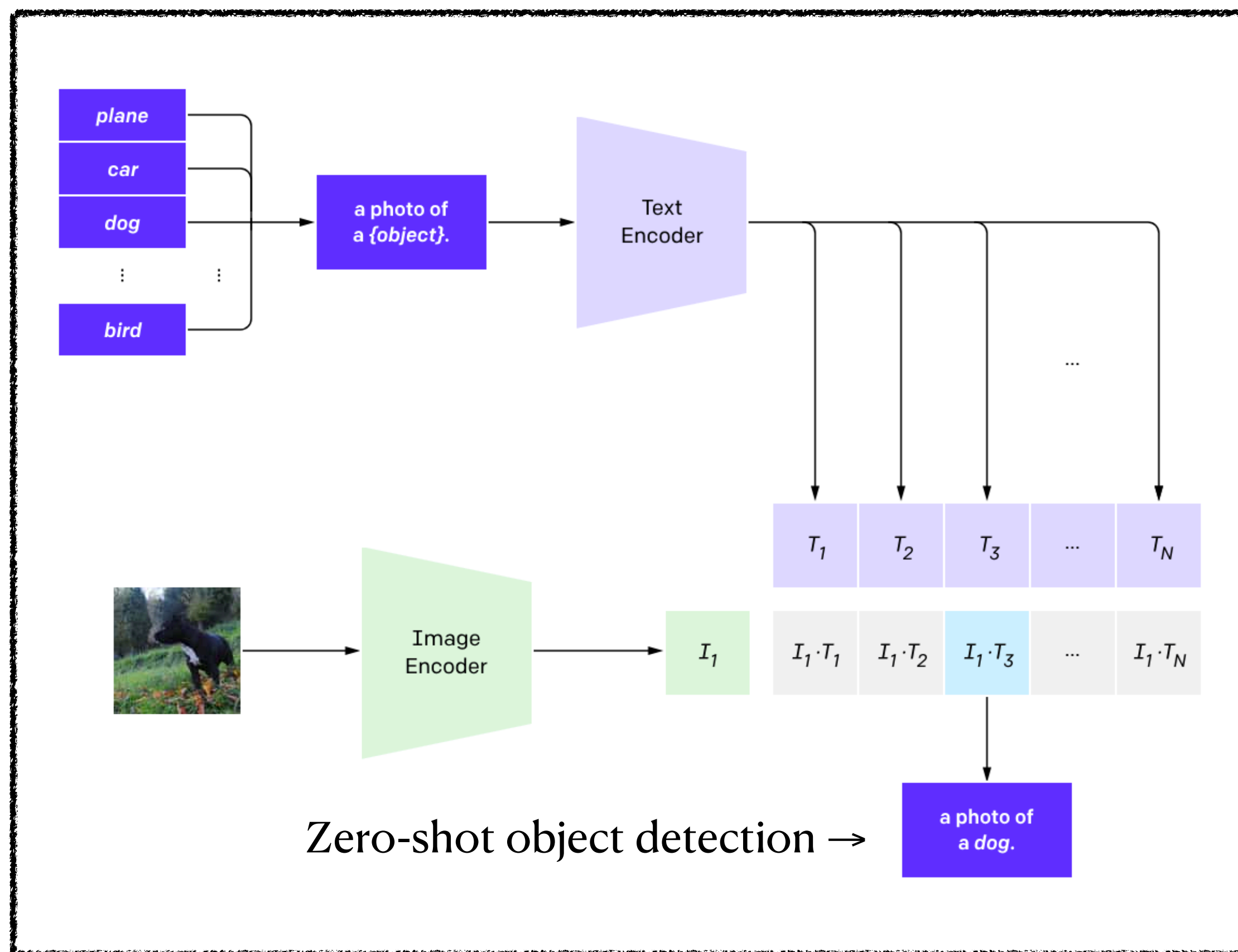
Training using Contrastive Loss: **pull similar images closer**, **push different images apart**



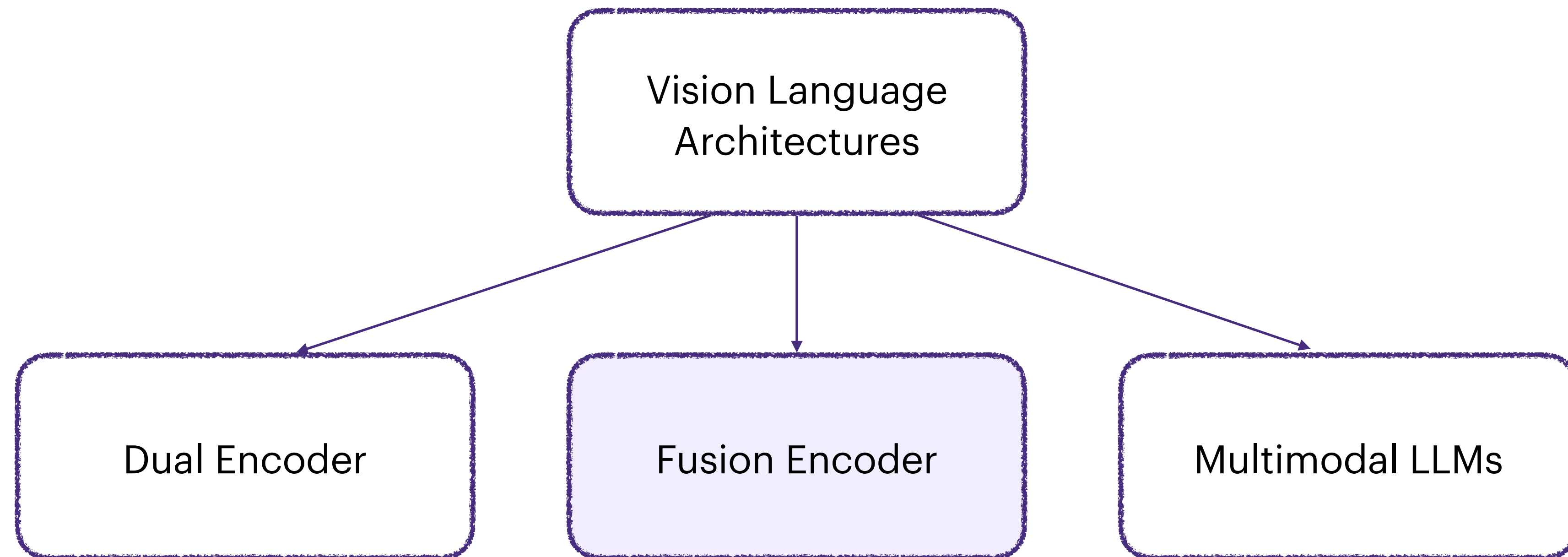


# Using CLIP

## Capabilities: Zero-shot inference

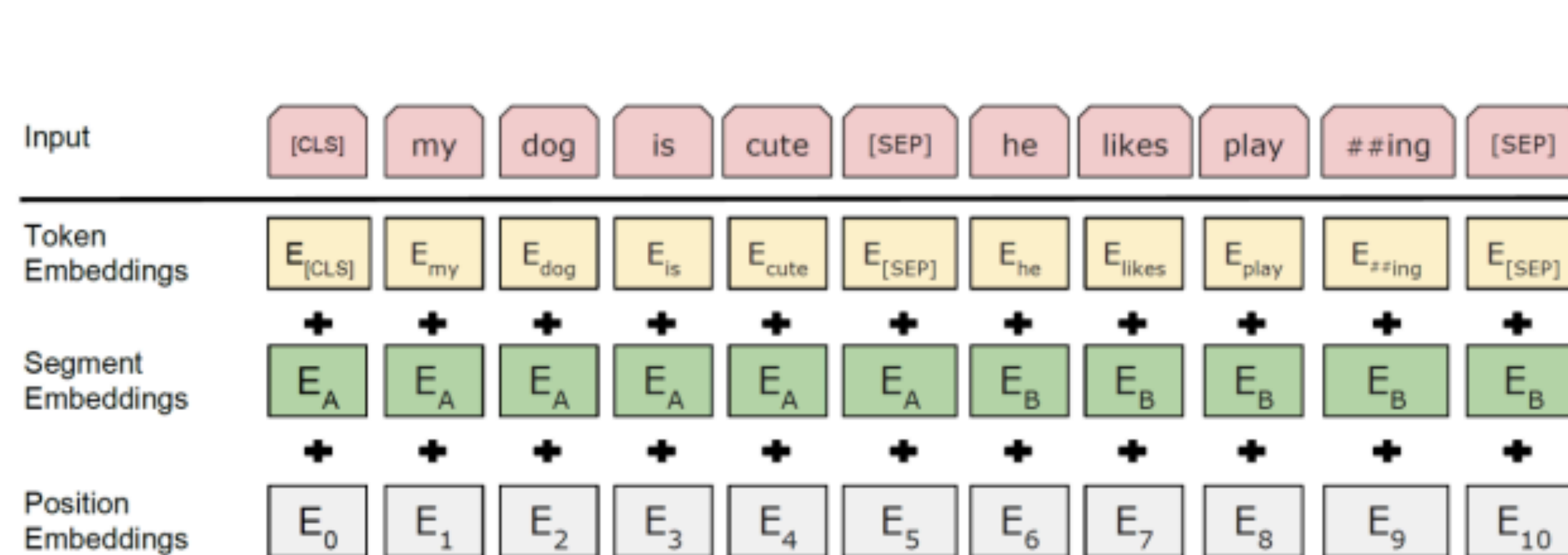


# Vision Language Models

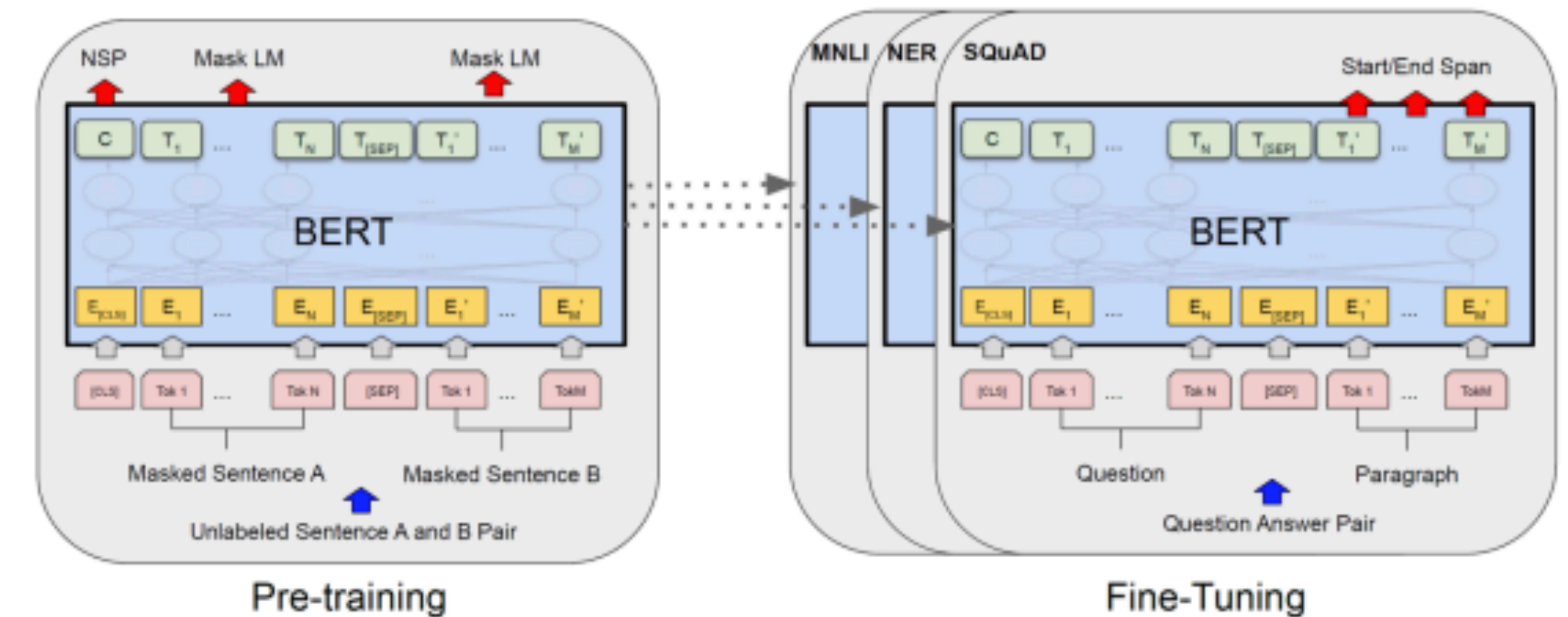


# Revisiting BERT...

Flexible and powerful in aggregating and aligning word features



Embedded features in BERT



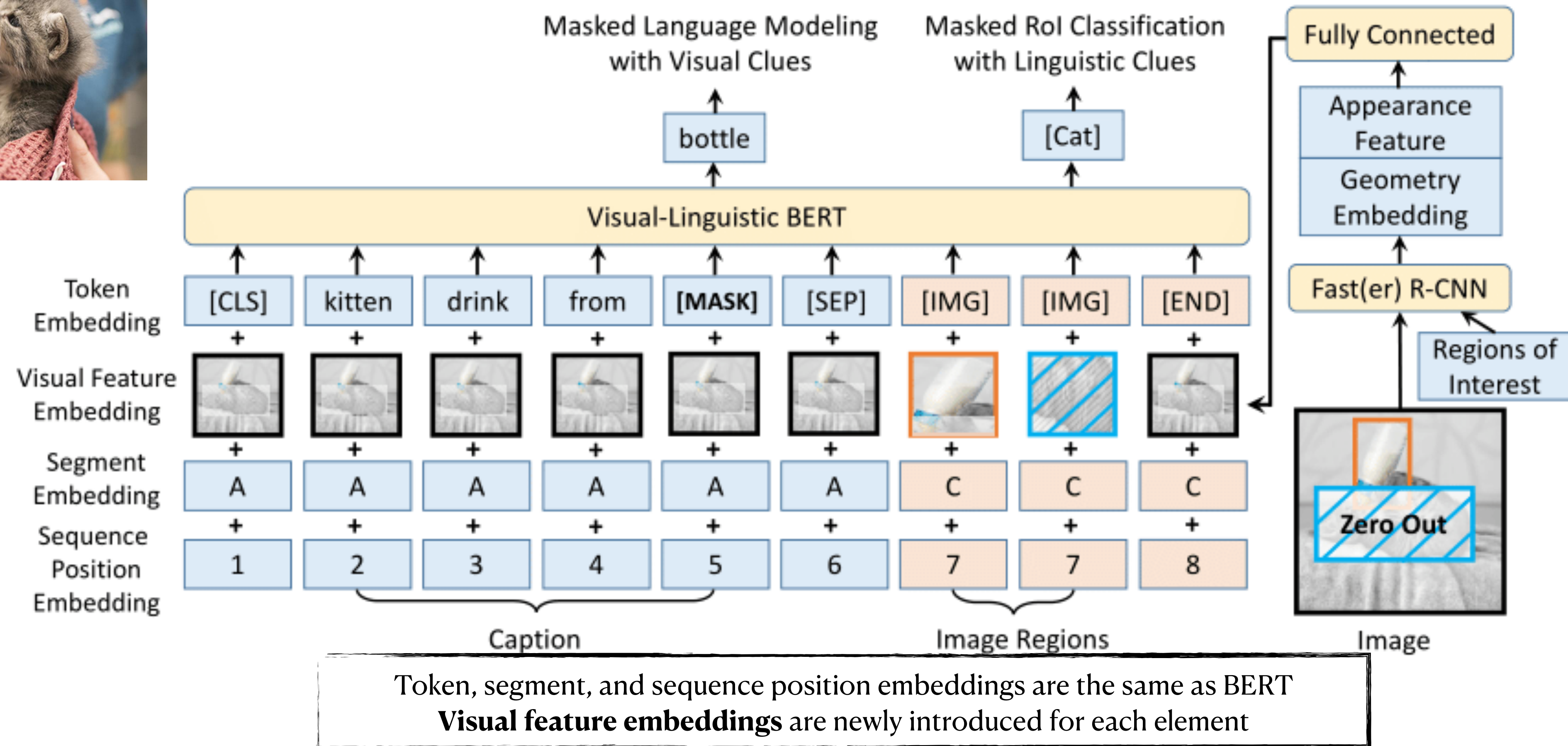
Pre-training & finetuning of BERT



# VL-BERT

## Architecture

- kitten drinking from [MASK]
- “kitten drinking from bottle”





# VL-BERT

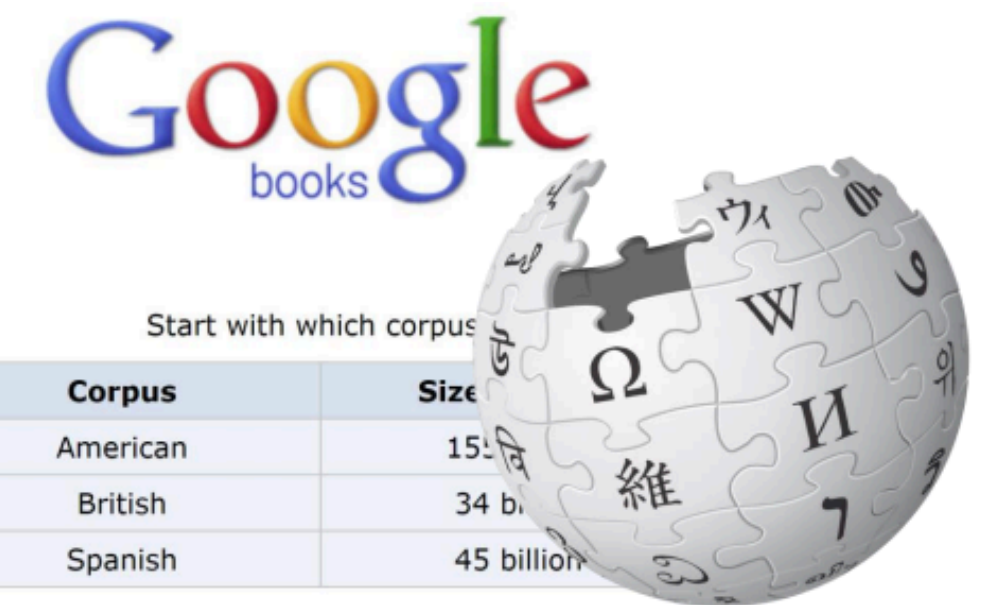
## Pretraining

### Conceptual Captions Pre-training

- Input: <Caption 🗨️, Image 🖼️>
- Task #1: Masked Language Modeling with Visual Clues
  - In the above figure, “**kitten drinking from [MASK]**”, it could be any containers, such as “bowl”, “spoon” and “bottle”. But with visual clues, the network should predict the masked word as “bottle”.
- Task #2: Masked RoI (Region of Interest) Classification with Linguistic Clues
  - In the above figure, the RoI corresponding to cat in image is masked out, and the corresponding category cannot be predicted from any visual clues. But with the input caption of “**kitten drinking from bottle**”, the model can infer the category such as “a cat” by exploiting the linguistic clues.



Conceptual Captions [ACL 2018]



Start with which corpus	
Corpus	Size
American	15.1 billion
British	34 billion
Spanish	45 billion

### BooksCorpus & English Wikipedia Pre-training

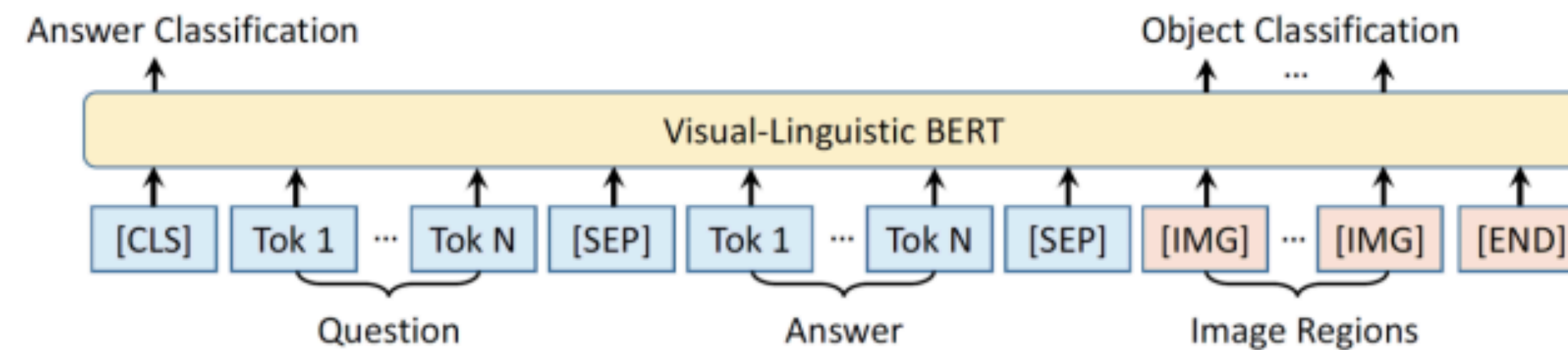
- Input: < Text 📖, Null>
- Task: Standard Masked Language Modelling (similar to BERT)

WIKIPEDIA  
The Free Encyclopedia

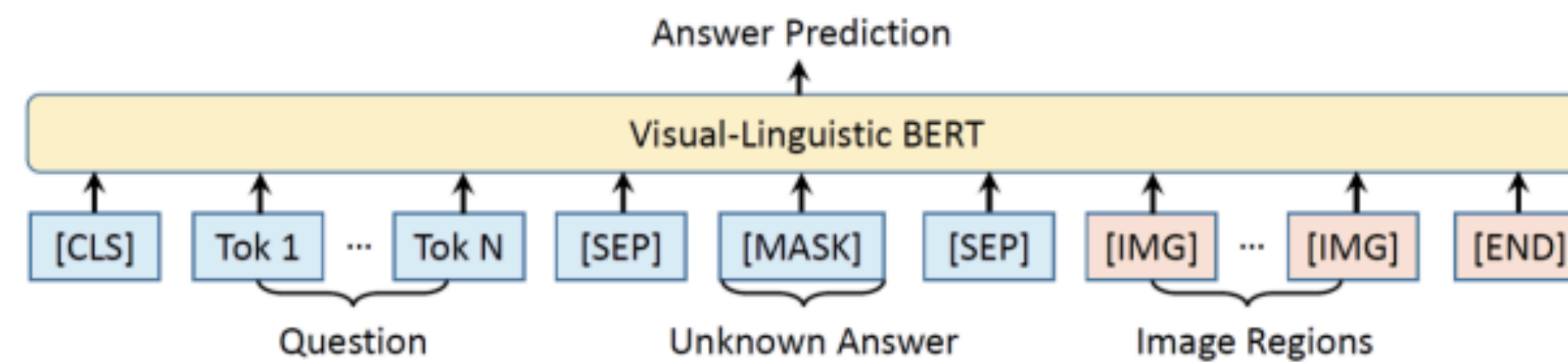
BooksCorpus [ICCV 2015] & English Wiki

# VL-BERT

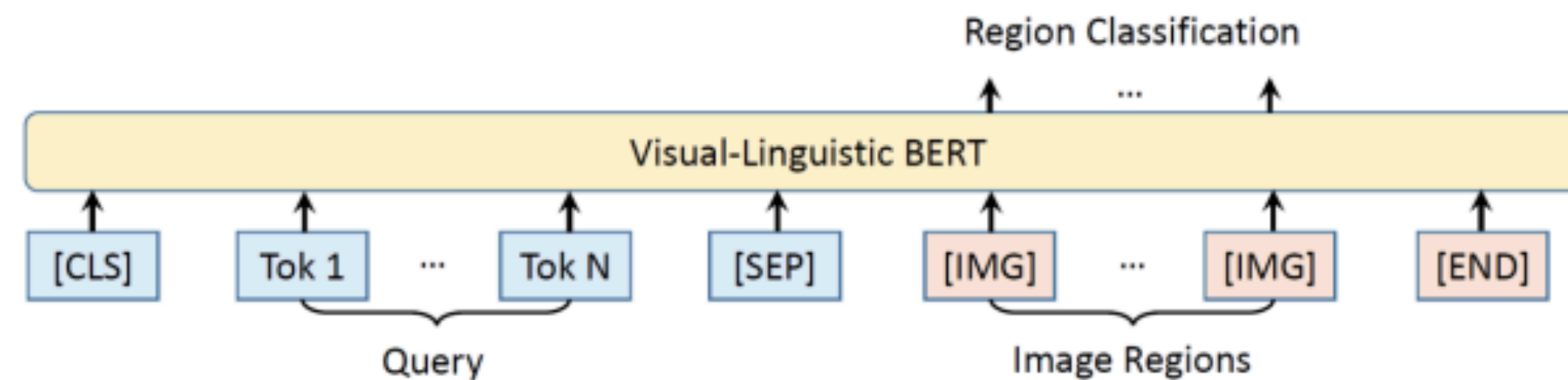
## Finetuning



(a) Input and output format for Visual Commonsense Reasoning (VCR) dataset



(b) Input and output format for Visual Question Answering (VQA) dataset



(c) Input and output format for Referring Expression task on RefCOCO+ dataset



# VL-BERT

## Capabilities

Model	Q $\rightarrow$ A		QA $\rightarrow$ R		Q $\rightarrow$ AR	
	val	test	val	test	val	test
R2C (Zellers et al., 2019)	63.8	65.1	67.2	67.3	43.1	44.0
ViLBERT (Lu et al., 2019) <sup>†</sup>	72.4	73.3	74.5	74.6	54.0	54.8
VisualBERT (Li et al., 2019b) <sup>†</sup>	70.8	71.6	73.2	73.2	52.2	52.4
B2T2 (Alberti et al., 2019) <sup>†</sup>	71.9	72.6	76.0	75.7	54.9	55.0
VL-BERT <sub>BASE</sub> w/o pre-training	73.1	-	73.8	-	54.2	-
VL-BERT <sub>BASE</sub>	73.8	-	74.4	-	55.2	-
VL-BERT <sub>LARGE</sub>	75.5	75.8	77.9	78.4	58.9	59.7

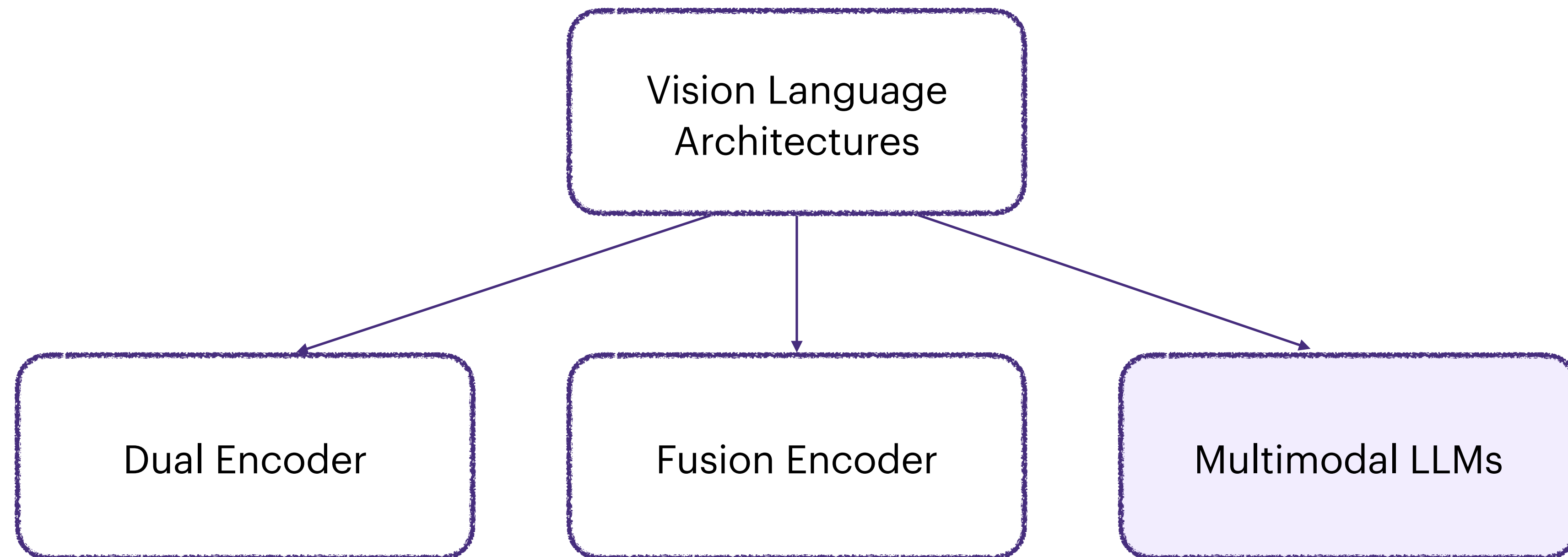
**VCR**

Model	test-dev	test-std
BUTD (Anderson et al., 2018)	65.32	65.67
ViLBERT (Lu et al., 2019) <sup>†</sup>	70.55	70.92
VisualBERT (Li et al., 2019b) <sup>†</sup>	70.80	71.00
LXMERT (Tan & Bansal, 2019) <sup>†</sup>	72.42	72.54
VL-BERT <sub>BASE</sub> w/o pre-training	69.58	-
VL-BERT <sub>BASE</sub>	71.16	-
VL-BERT <sub>LARGE</sub>	71.79	72.22

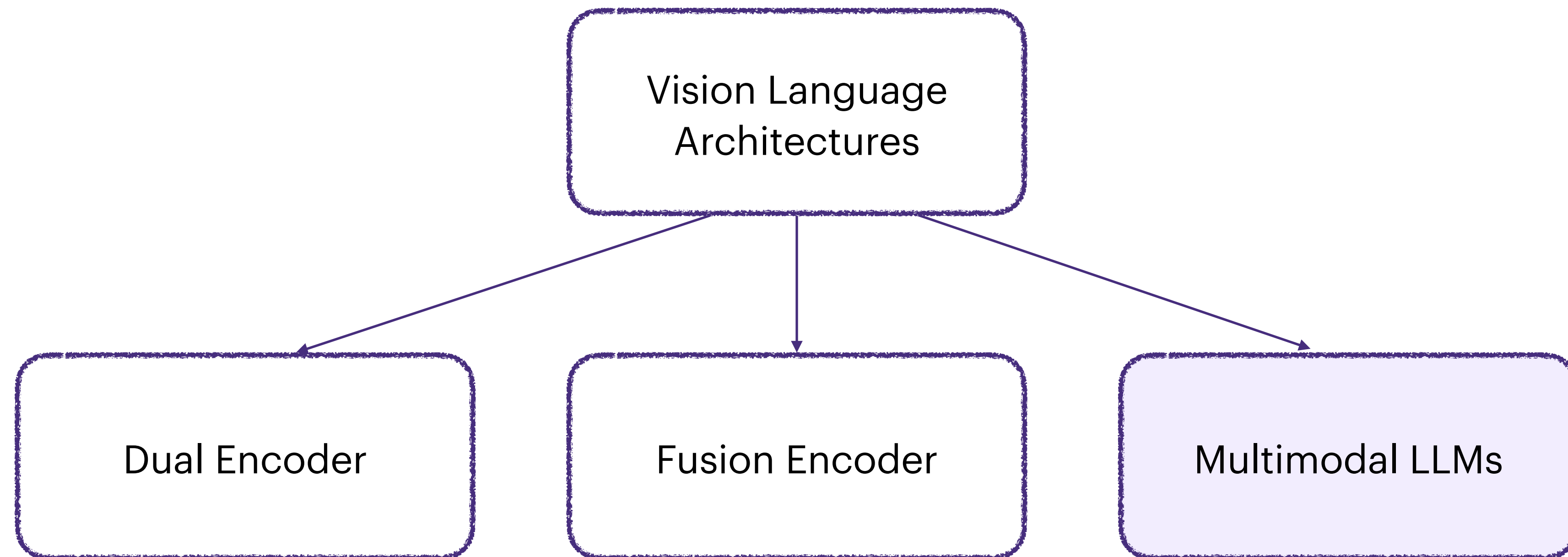
**VQA**

**Still far from human performance. Yet, VL-BERT was among the first to introduce and popularize this architecture.**

# Vision Language Models



# Vision Language Models

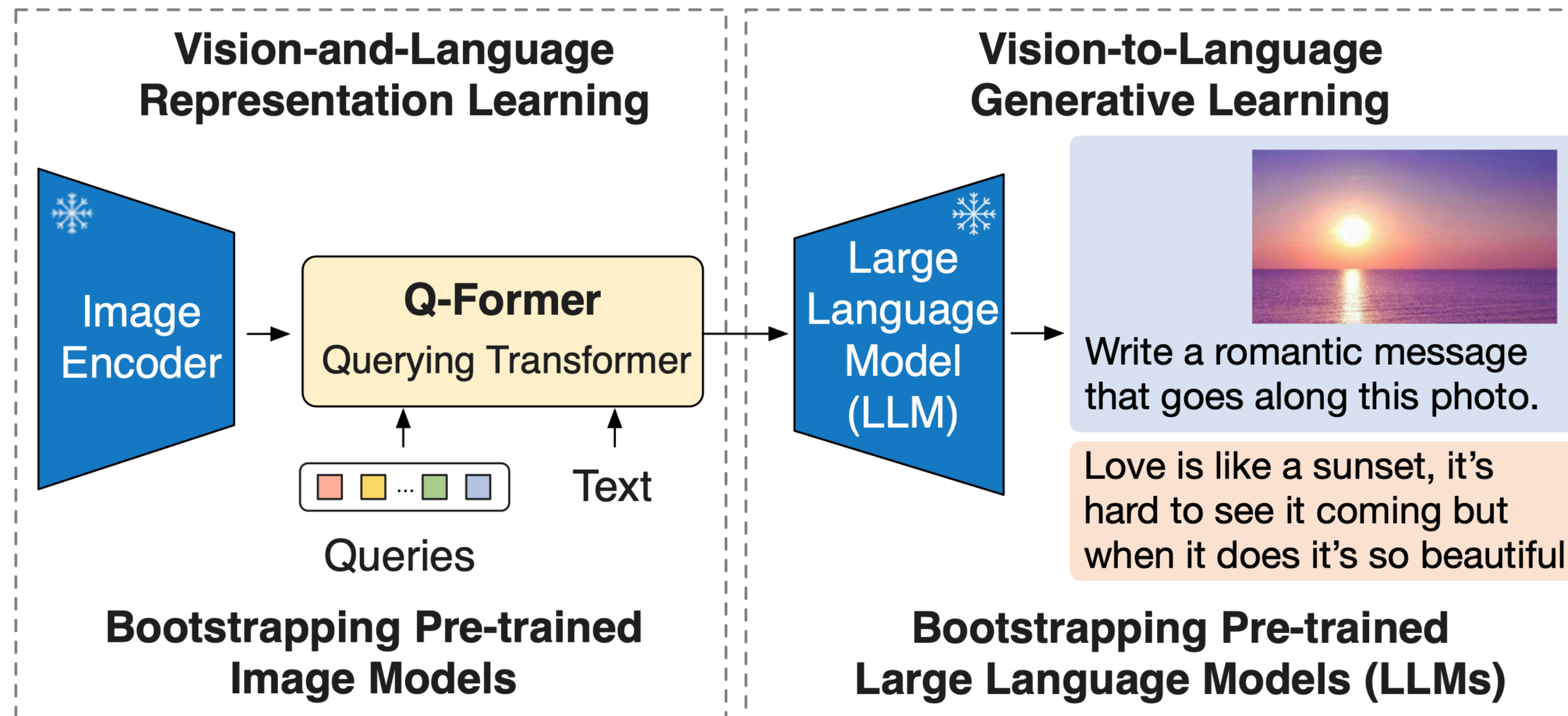


🤔 We trained huge LLMs already 💰... can we make them understand other modalities?



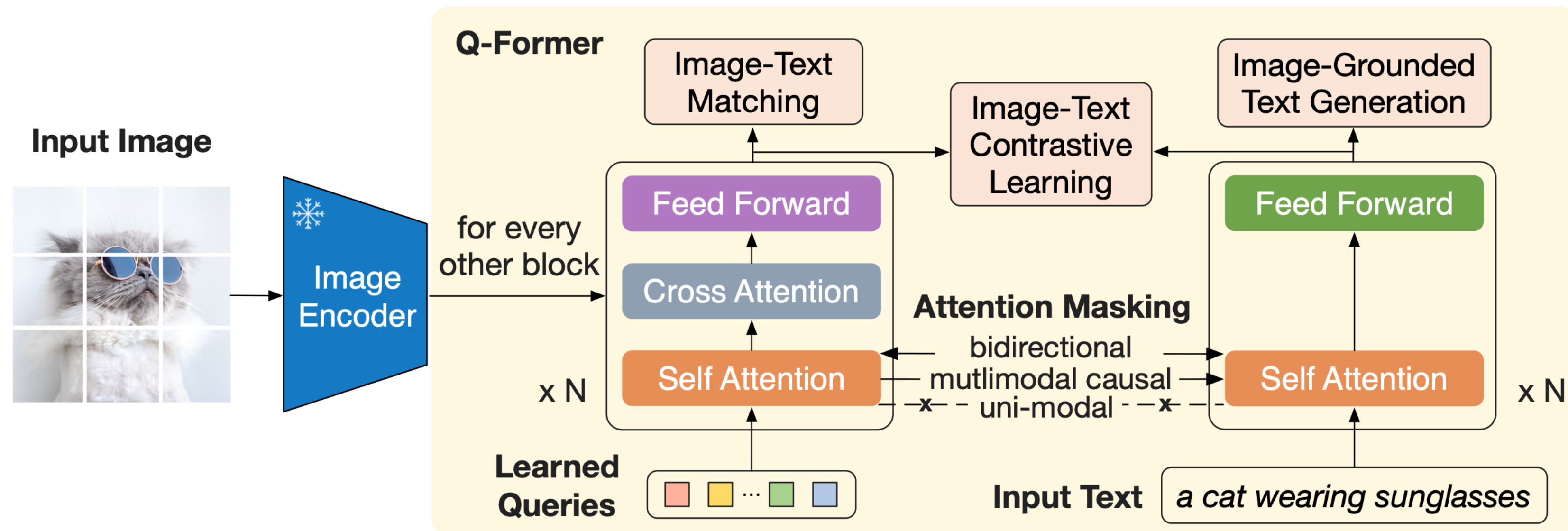
# BLIP-2

## Architecture



A **Q-Former** is trained to connect a frozen image encoder to a frozen LLM: image tokens are converted to tokens readable by the LLM. Prompt tuning: projection layer for visual tokens

## How is the Q-Former Trained?




Queries: “soft visual prompts” — 🔥 Learnable (what to see in the image?)

## Advantage of LLM and Image Encoder: compute requirements for training



# BLIP-2

## Capabilities & Examples




Is this photo unusual?

Yes, it's a house that looks like it's upside down.

How could someone get out of the house?

It has a slide on the side of the house.




What are shown in the photo?

A man and a chicken.

What does the man feel and why?

He is scared of the chicken because it is flying at him.



What are the ingredients I need to make this?

Pepperoni, mozzarella cheese, pizza sauce, olive oil, salt, pepper, basil.

What is the first step?

Place the pizza dough on a baking sheet, brush with olive oil, sprinkle with salt, pepper, and basil.

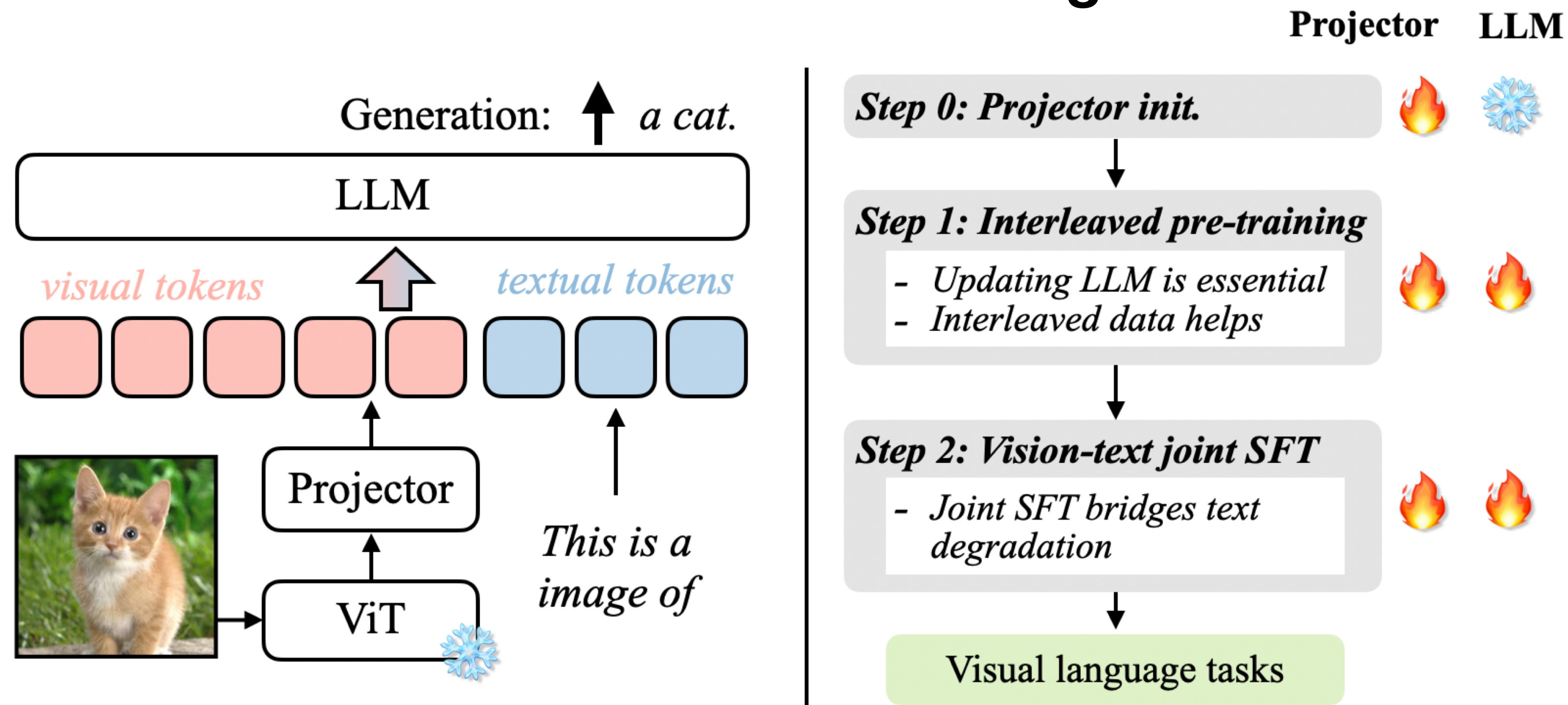
1 Because it is based on an LLM, we can **chat** with it (unlike VL-BERT)

2 Enables **zero-shot** and **few-shot** tasks



# VILA

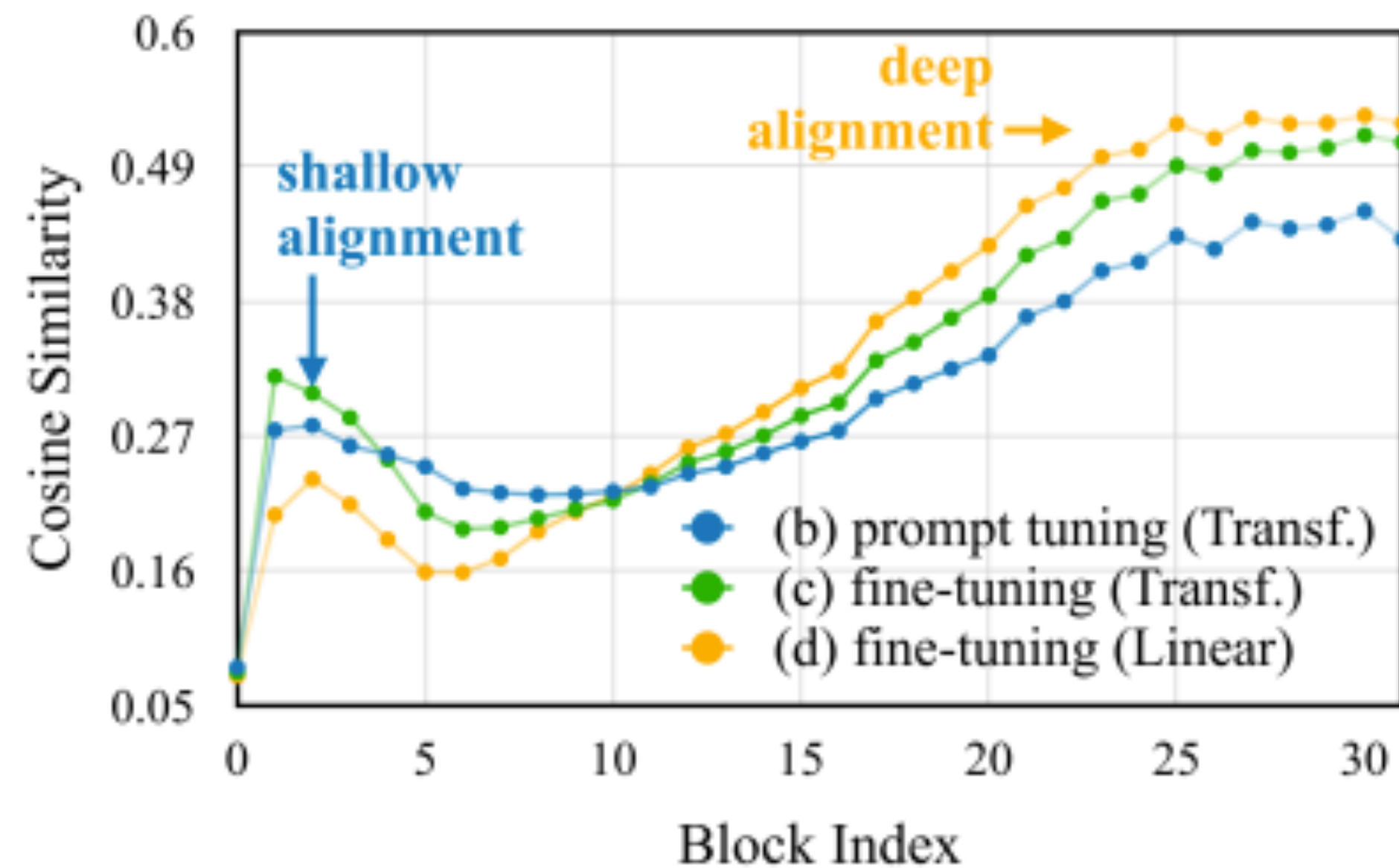
## Architecture & Training



All steps use next token prediction objective. Prompt-tuning to support visual tokens can only enable shallow alignment, while **fine-tuning the LLM** leads to alignment at deeper layers

# VILA

## Training Recipe






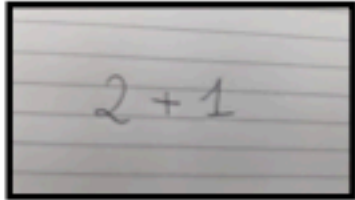
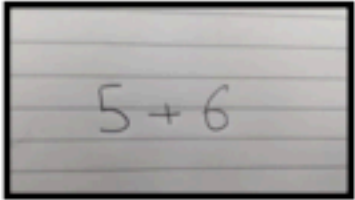
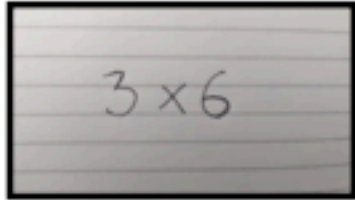



All steps use next token prediction objective. Prompt-tuning to support visual tokens can only enable shallow alignment, while **fine-tuning the LLM** leads to alignment at deeper layers 🔥

Image resolution is more important than the number of visual tokens: Increasing image resolution, particularly from 224 to 336, significantly improves the accuracy of tasks



# VILA

## Capabilities

Input few shot examples + target image			Output
			LLaVA-1.5: Soulemes. Ours: Soulomes.
Underground.	Congress.	?	
			LLaVA-1.5: 3x6=18 Ours: 3x6=18
2+1=3	5+6=11	?	
			LLaVA-1.5: Surrealism Ours: Impressionism
Romanticism	Surrealism	?	



**Prompt:** <img>\nI am getting just two custom pizza for me and my friend. How much should I pay in total according to the image?

**Answer:** According to the image, you should pay **\$11.99** for two custom pizzas.

**Prompt:** ... + *Let's think step-by-step.*

**Answer:** The image shows a chalkboard menu with a special for today, which is to create your own pizza. The price for this special is \$9.99. Since you are getting two custom pizzas, you should pay  $\$9.99 \times 2 = \$19.98$  for the two pizzas. So, the answer is **\$19.98**.

- 1 Performs **few-shot** tasks, can support multiple images
- 2 Enables **COT** reasoning



# Video Models

## From Image to Video

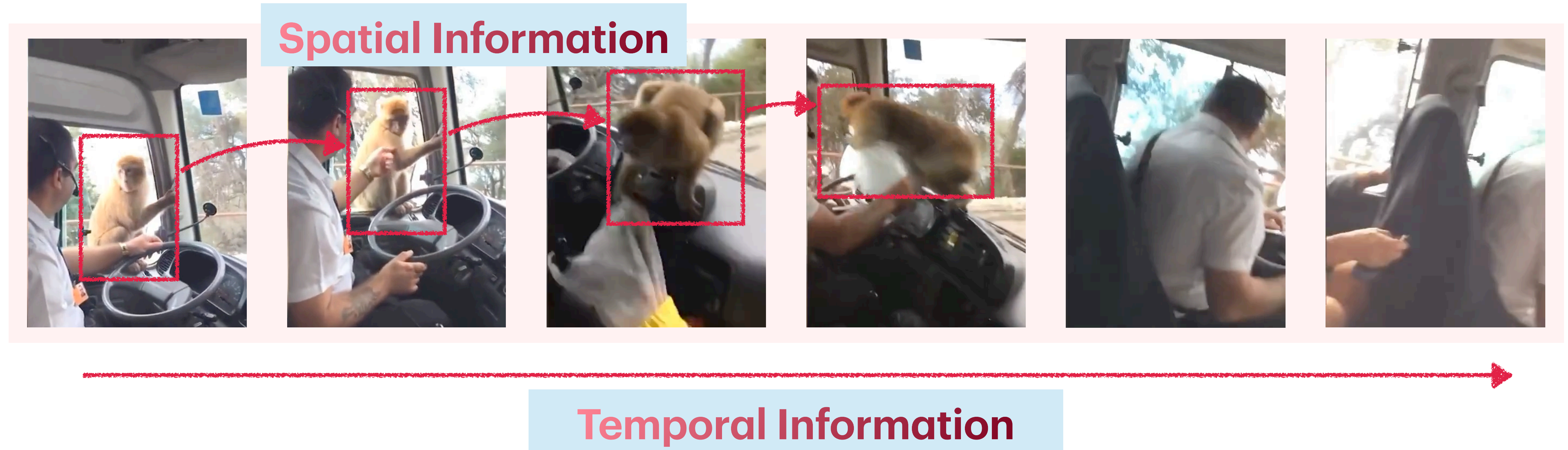


Videos → Collection of **frames** that are **sequentially** inter-related to each other



# Video Models

## From Image to Video



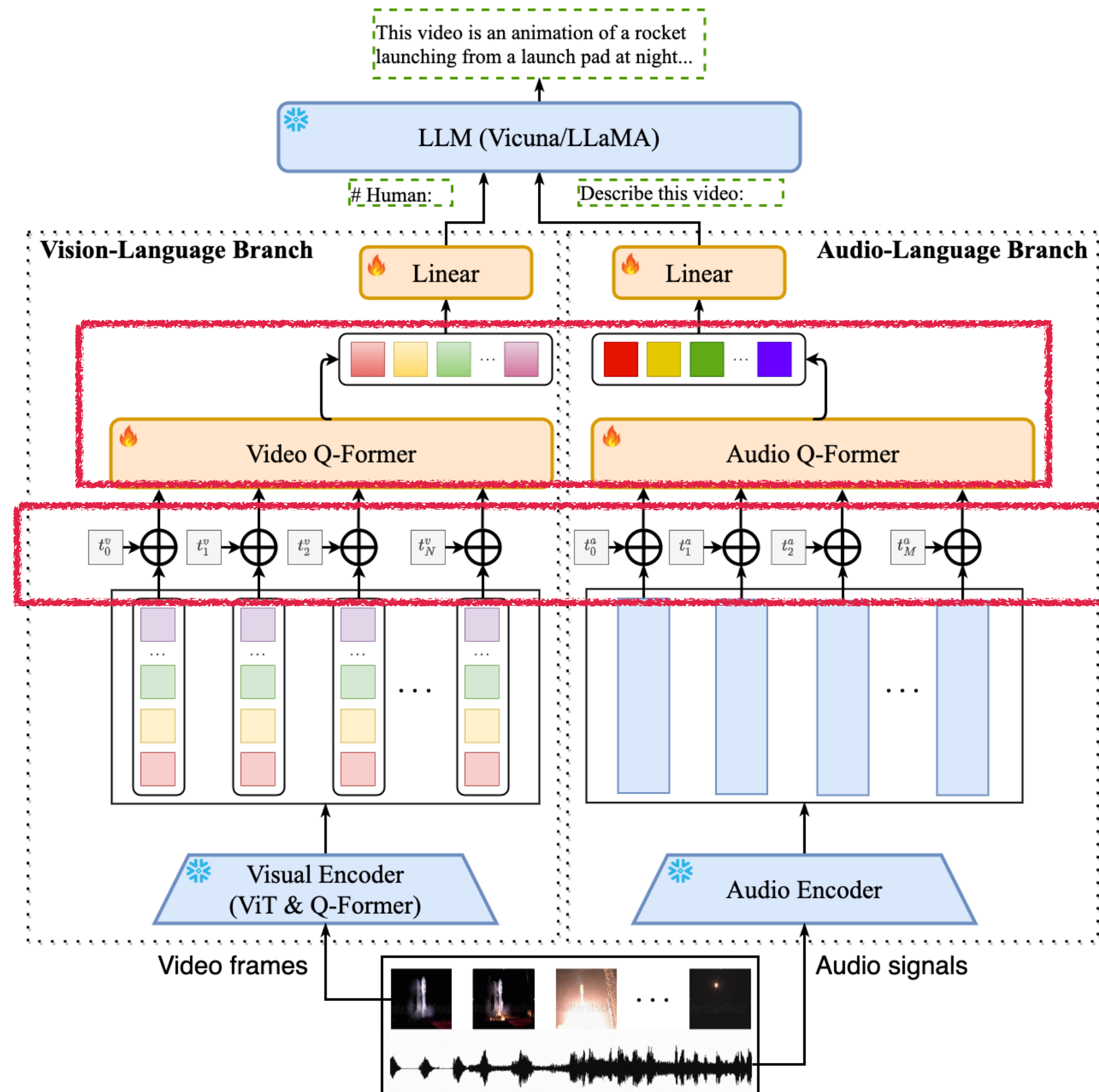
Videos → Collection of **frames** that are **sequentially** inter-related to each other

Challenge: Models must be trained to understand spatiotemporal relationships between frames



# VideoLLaMA

## Extending Q-Former to Video and Audio



Video = list of frames (8 to 64 images)  
Audio = list of audio clips (2s)

The example shows a video input of a cherry blossom-lined river with a boat and a cityscape. The video is represented as a sequence of frames. A prompt is generated: "Summarize this video in one sentence." The LLM (Vicuna/LLaMA) responds with: "The video shows a beautiful scenery of a **cherry blossom-lined** river **flowing by a boat** on the water, and a cityscape with **tall buildings** in the background." A second prompt is generated: "What direction is the ship going". The LLM responds with: "The ship is going towards the **right** side of the video."



# Comparing Model Types

## When to use what?

Architecture	Strengths	Weaknesses	Best for
Dual Encoders (e.g. CLIP)	<ul style="list-style-type: none"><li>✓ Simpler architecture with separate vision and text encoders</li><li>✓ Scalable and efficient for retrieval</li></ul>	<ul style="list-style-type: none"><li>● Limited interaction between modalities</li><li>● May miss cross-modal context</li></ul>	<ul style="list-style-type: none"><li>- Retrieval tasks (zero-shot)</li><li>- Document search</li><li>- Classification</li><li>- Captioning</li></ul>
Fusion Encoders (e.g. VL-BERT, Flava)	<ul style="list-style-type: none"><li>✓ Unified representation of vision and text</li><li>✓ Stronger integration of cross-modal relationships</li></ul>	<ul style="list-style-type: none"><li>● Harder to scale and optimize due to complex interactions</li><li>● May struggle with very large datasets</li></ul>	Tasks requiring deep interaction between modalities (e.g., captioning, VQA)
Multimodal LLMs (e.g. VILA, BLIP, LLaVA)	<ul style="list-style-type: none"><li>✓ Strong language understanding</li><li>✓ Flexible architecture</li><li>✓ Efficient to train</li><li>✓ Upgradable with newer LLMs</li></ul>	<ul style="list-style-type: none"><li>● May not effectively model visual details without pre-training on a multimodal dataset</li></ul>	<ul style="list-style-type: none"><li>- Prompting + zero-shot</li><li>- Complex reasoning tasks</li><li>- Chat</li><li>- Video understanding</li></ul>

# Outline

## Reasoning about vision and language

- Motivation
- Visual Commonsense Reasoning tasks
- Vision and language representations and models
- **Open problems and future directions**

# **Black Swan: Abductive and Defeasible Video Reasoning in Unpredictable Events**

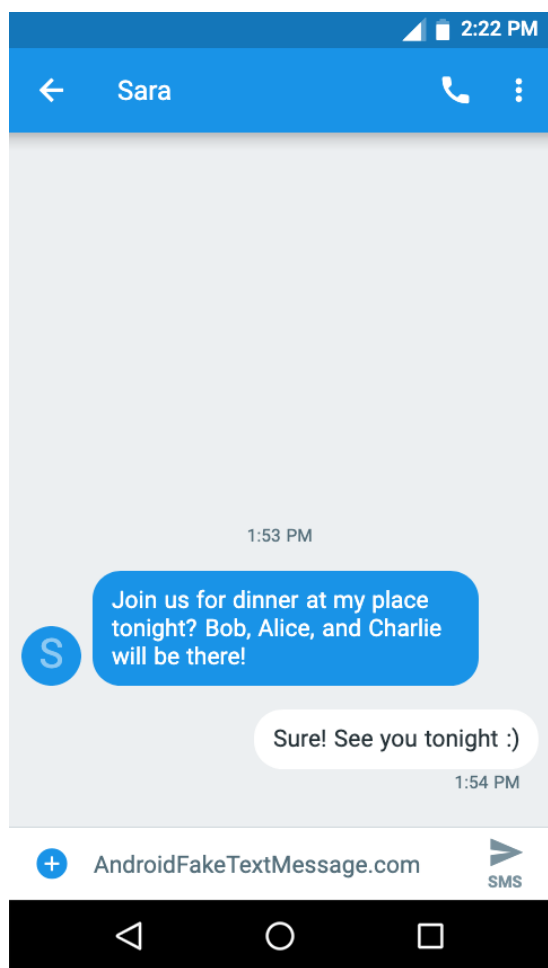
**Aditya Chinchure\*, Sahithya Ravi\*, Raymond Ng, Vered Shwartz, Boyang Li, Leonid Sigal**  
*Under Review*



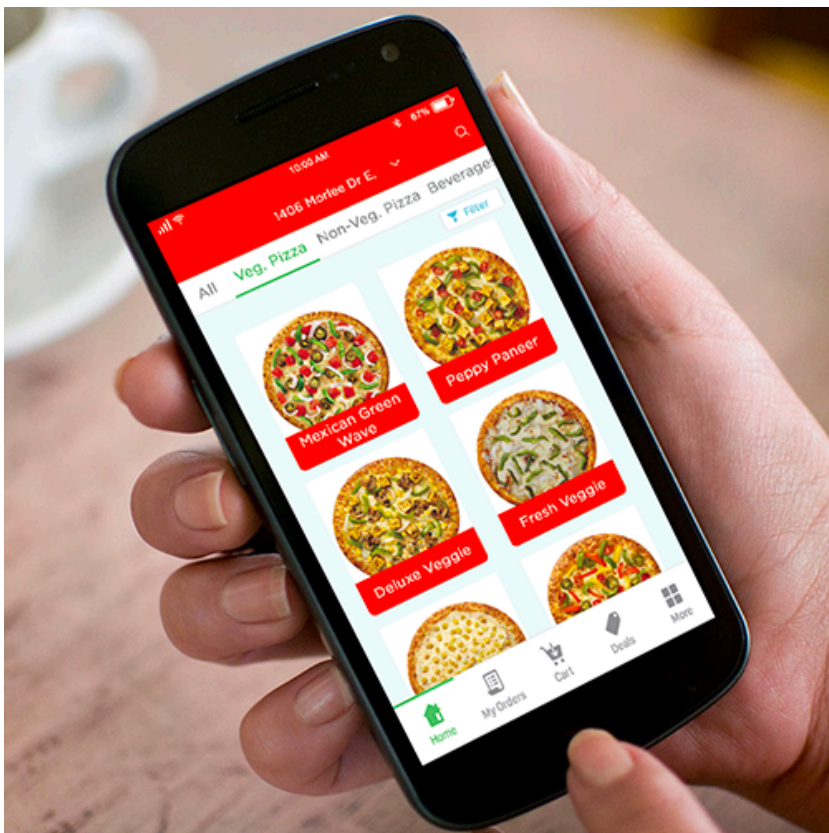
# Recap

## Abductive Reasoning

Reason about the most plausible explanation for incomplete observations.



Sara wanted to make dinner for some guests.



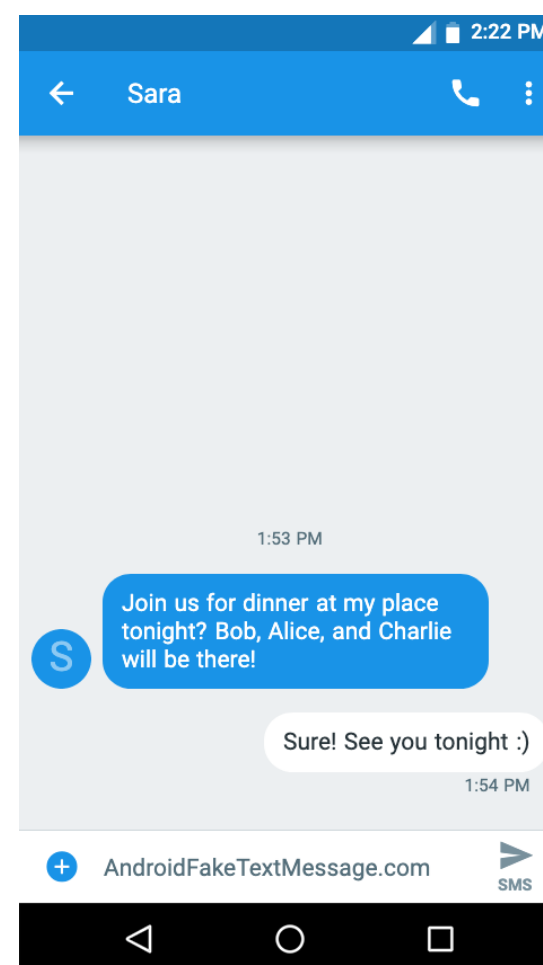
She had to order pizza for her friends instead.

Charles Sanders Peirce. Collected papers of Charles Sanders Peirce, volume 5. Harvard University Press, 1965.

# Recap

## Abductive Reasoning

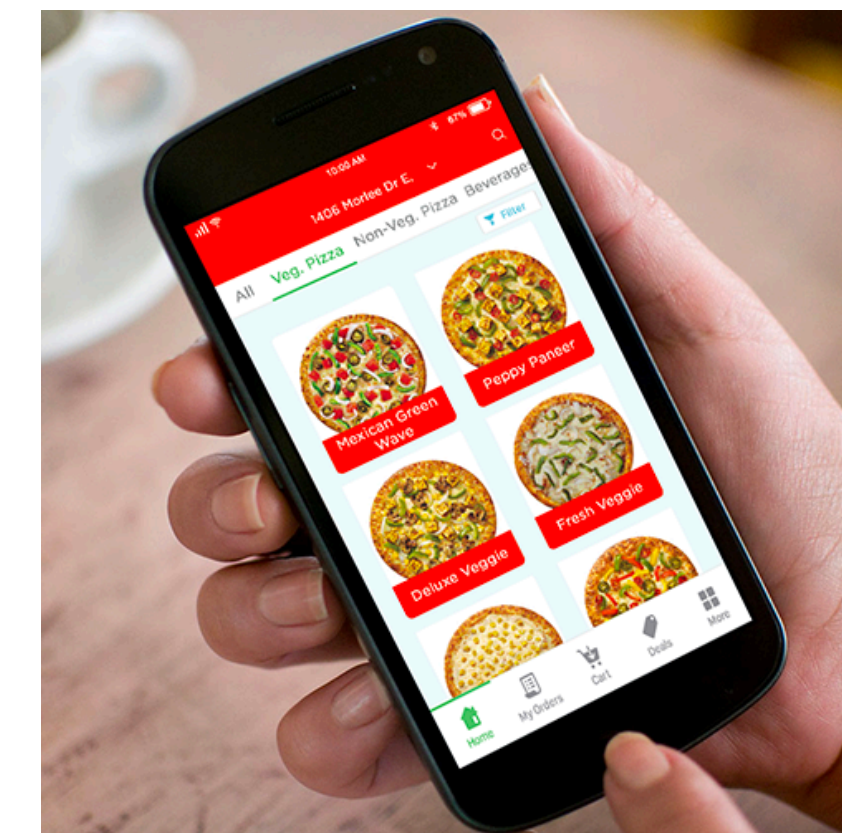
Reason about the most plausible explanation for incomplete observations.



Sara wanted to make dinner for some guests.



But she didn't know how to cook.



She had to order pizza for her friends instead.

## Recap

# Defeasible Inference in Natural Language

An update  $U$  is called a **weaken**er if, given a premise  $P$  and hypothesis  $H$ , a human would most likely find  $H$  *less likely to be true* after learning  $U$ ; if they would find  $H$  *more likely to be true*, then we call  $U$  a **strengthen**er.

$P$ : Tweety is a bird. 

$H$ : Tweety flies. 

Weaken

er: Tweety is a penguin. 

Strengthen

er: Tweety is on a tree. 

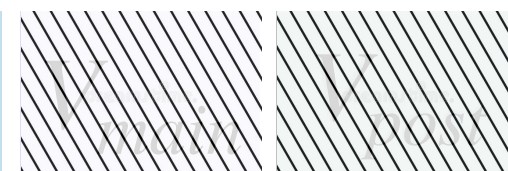


# Black Swan: Tasks



Forecaster

$V_{pre}$



Given  $V_{pre}$ , what could happen next?

NEW "The car suddenly breaks down in the middle of the road."

Detective

$V_{pre}$



$V_{post}$

Given  $V_{pre}$  and  $V_{post}$ , what could happen in the middle?

✗ "The car suddenly breaks down in the middle of the road."

NEW "A pile of snow suddenly falls on top of the driver and passenger."

Reporter

$V_{pre}$



$V_{main}$

$V_{post}$

Given the entire video, explain what happened.

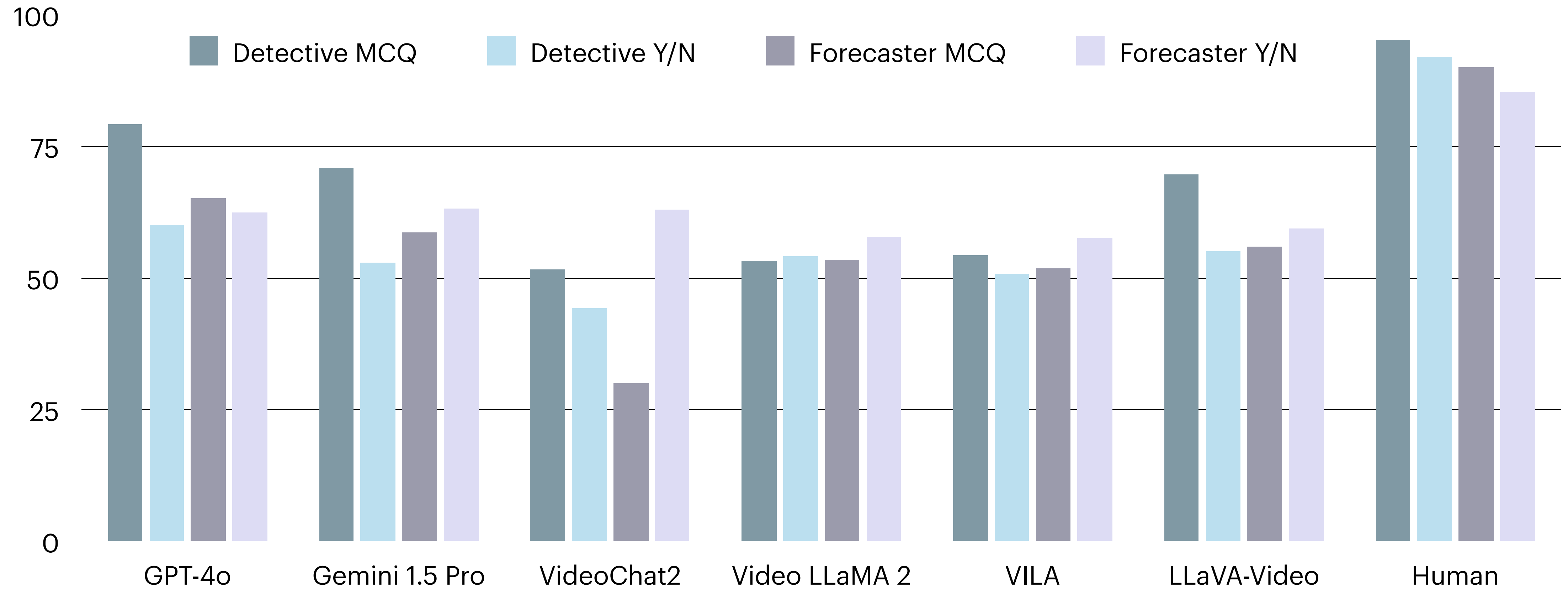
✓ "A pile of snow suddenly falls on top of the driver and passenger."

🎯 "A truck driving by splashes snow from the ground in the faces of the driver and passenger"

hidden part of the video NEW new explanation ✓ explanation valid ✗ explanation invalid 🎯 final explanation (caption)

BlackSwanSuite Comprises of three tasks to evaluate Video Reasoning

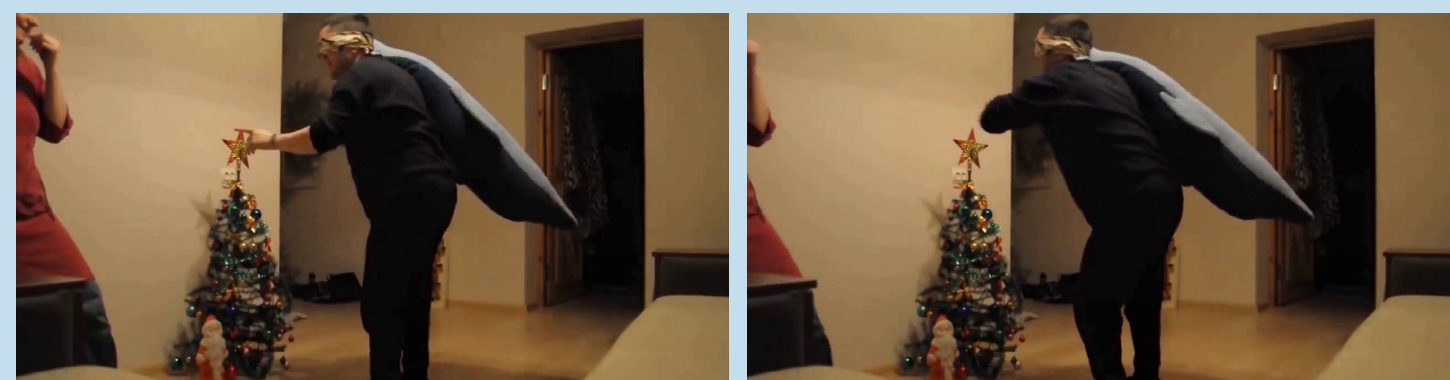
# Benchmarking



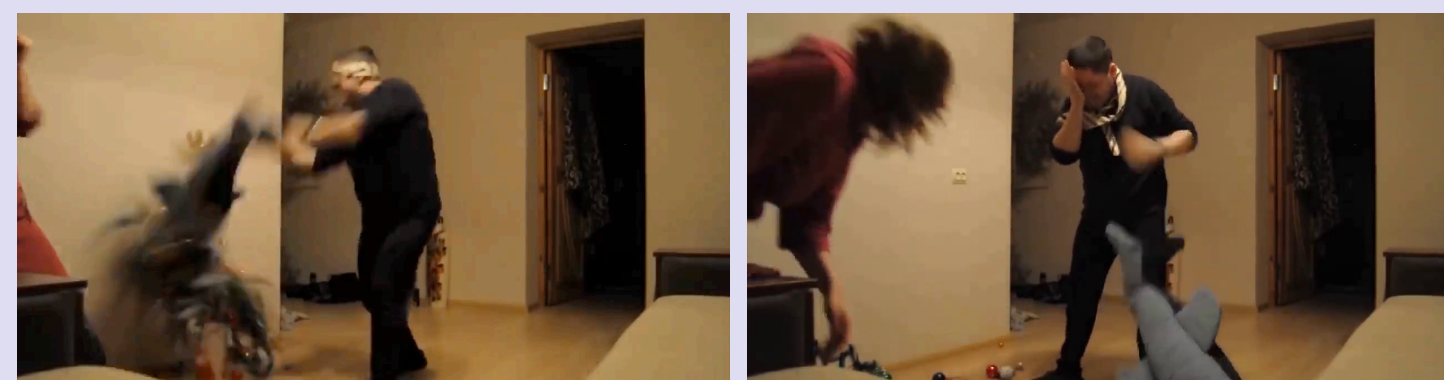
Humans outperform top models by ~25-30% on most tasks



# Qualitative Examples



Pre-event:  $V_{pre}$



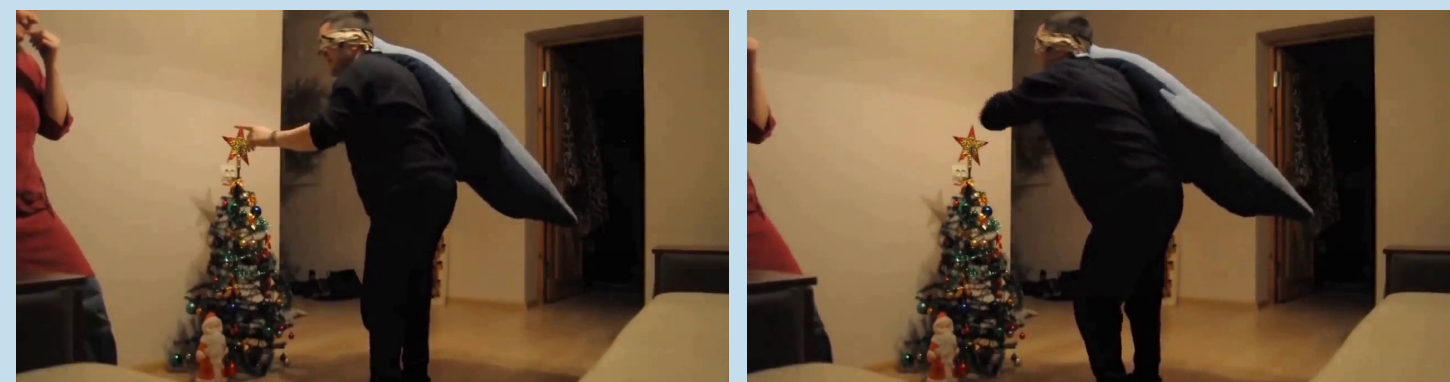
Main event:  $V_{main}$



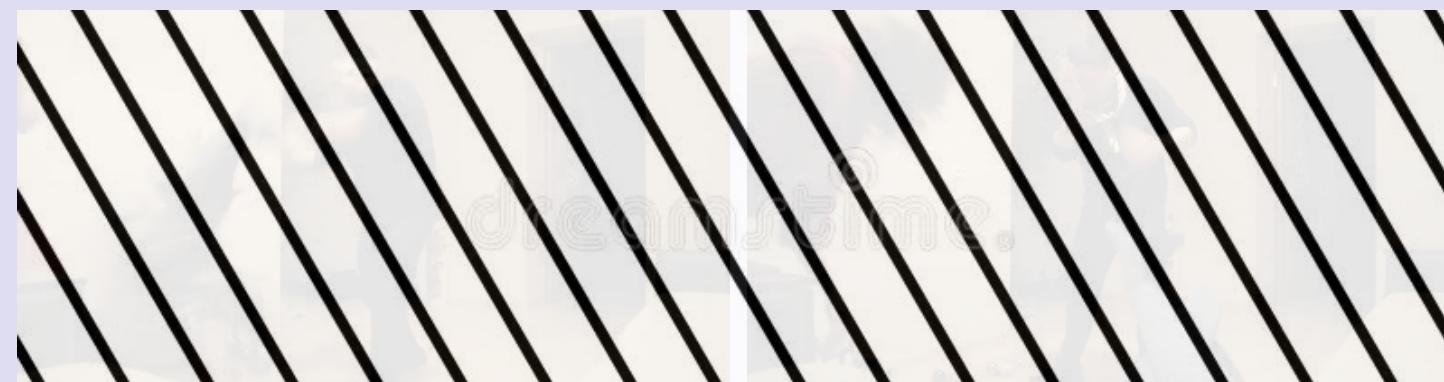
Post-event:  $V_{post}$



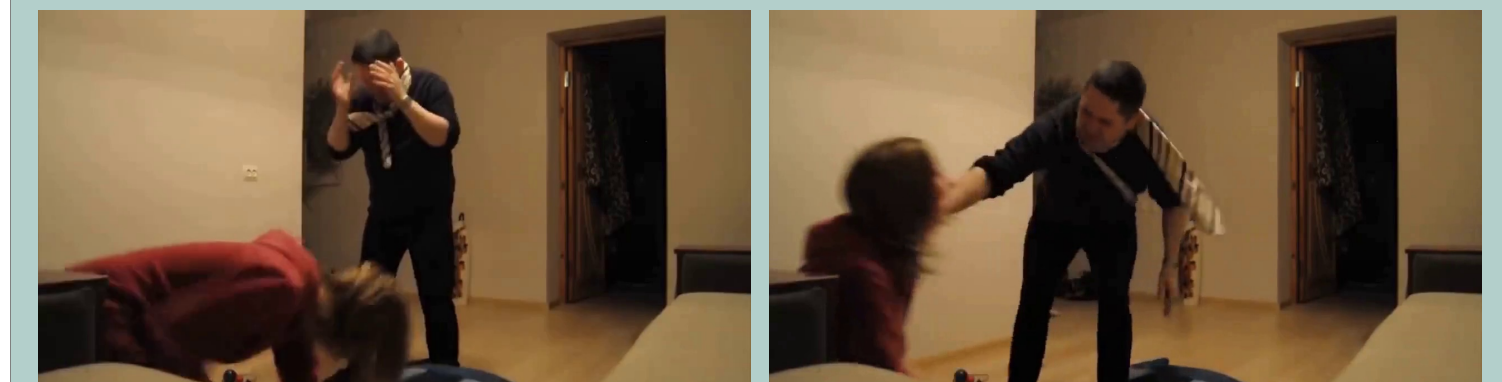
# Qualitative Examples



Pre-event:  $V_{pre}$



Main event:  $V_{main}$



Post-event:  $V_{post}$

Sample evaluation tasks for the above video:

Detective—MCQ:

Given:  $V_{pre}$  &  $V_{post}$

What happened in between?

- A. The man swings the object and twists around, causing himself to fall to the ground
- B. The man swings the object and hits the other person in the visual, as well as the Christmas tree.**
- C. The man will stand in a room with a Christmas tree while wearing a cape.

Ground Truth: B

Predicted: A — all models incorrect

Detective—Y/N: Given  $V_{pre}$  &  $V_{post}$

Validate the Hypothesis: “The mans swings the object and knocks down the Christmas tree”

Ground Truth: “Yes”

✓ Predicted “Yes”: VideoLlama2, VideoChat2

✗ Predicted “No”: GPT4o, Gemini, Vila, Llava-Video

Reporter—Y/N: Given  $V_{pre}$ ,  $V_{main}$ ,  $V_{post}$

Validate the Hypothesis: “The mans swings the object and hits the other person in the visual as well as the Christmas tree.”

Ground Truth: “No”

✗ Predicted “Yes”: All models, all are incorrect

Reporter—MCQ:

Given:  $V_{pre}$ ,  $V_{main}$ ,  $V_{post}$

What happens in the video?

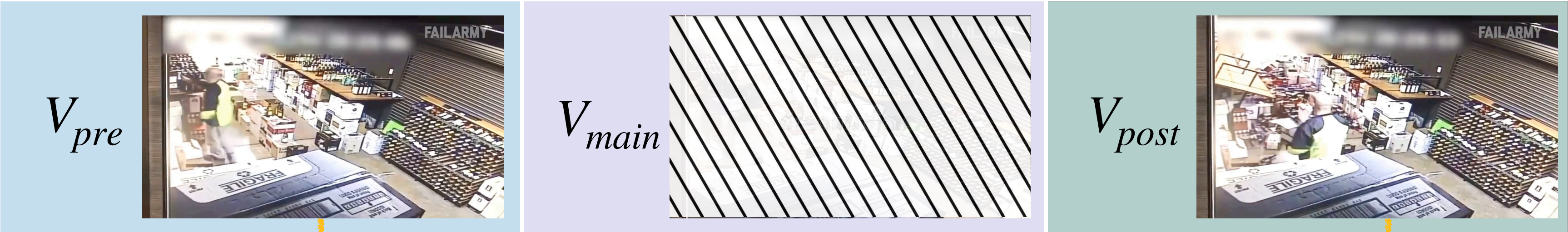
- A. The man swings the object and knocks down the Christmas tree which causes the ornaments to fly off and hit the bystander**
- B. The man swings the object and hits the other person in the visual as well as the Christmas tree
- C. The man swings the object and hits the other person in the visual

Ground Truth: A

Predicted: A — all models are correct



# What happens when humans assist with Perception & Comprehension?



👁 Perception

💡 Interpretation  
(Comprehension)

🤔 Reasoning

Person arranges wine bottles  
on shelf

Person standing in a liquor store  
in front of a messy shelf

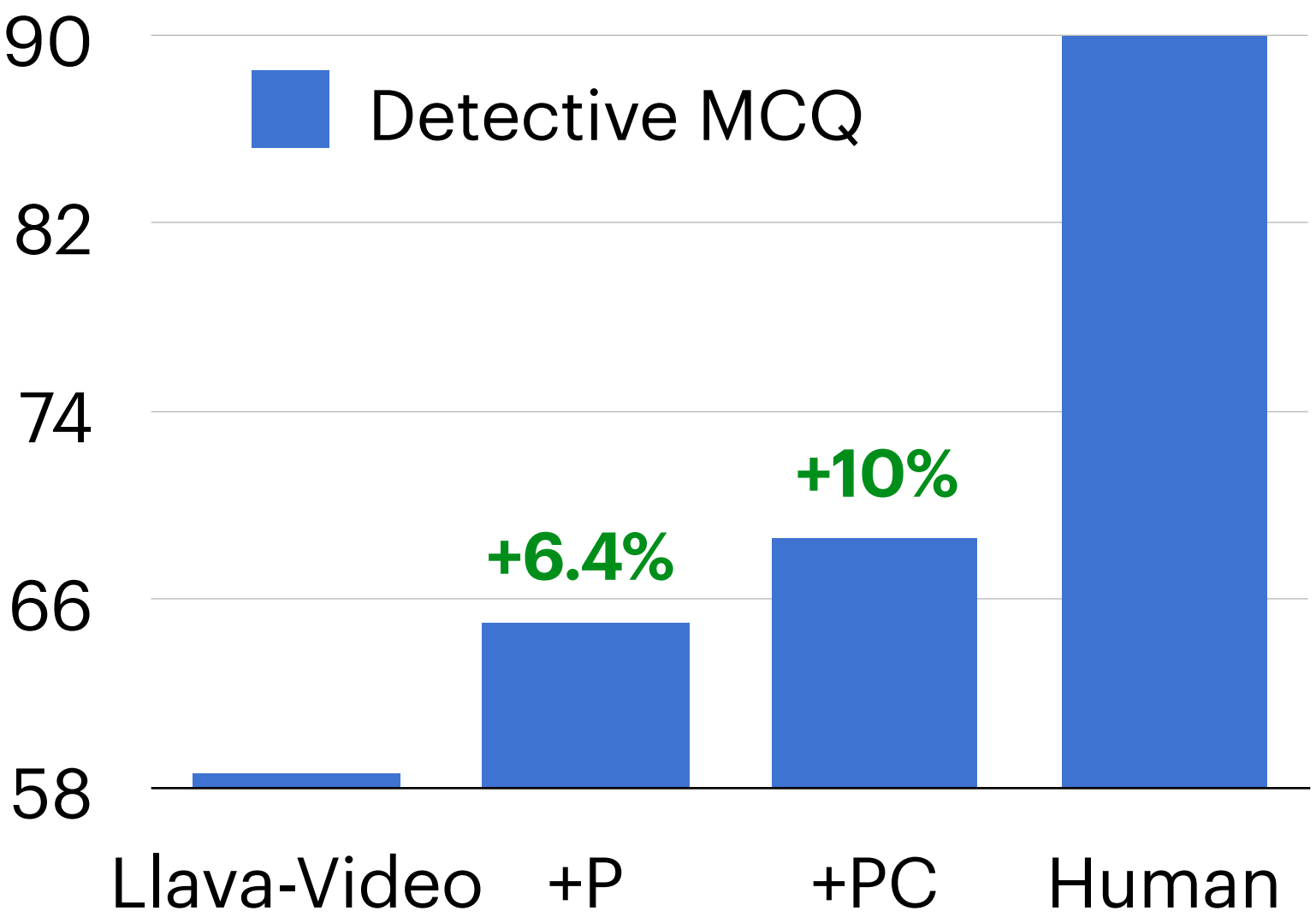
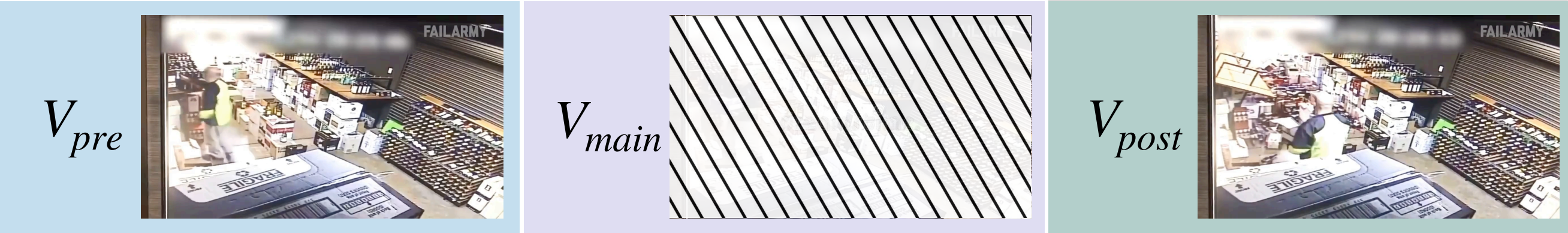
The shelf appears to have  
tipped over

What happened in the middle?

Answer...



# What happens when humans assist with Perception & Comprehension?



- A. As the guy carries the box of wine bottles, he begins to slip around while still carrying them.
- B. The guy throws the box of wine bottles in the air out of frustration and lets the bottles crash onto the floor all around him.
- C. As the man removes a box of wine bottles from the table, the table starts to wobble, causing the other boxes still on the table to start falling to the floor.

## Perception:

$V_{pre}$ : A man is removing a box of wine bottles from a shelf in a liquor storage area or liquor store. The area is closed up and presumably not open to the public or not a retail store.

$V_{post}$ : A man is standing with his back to the camera. Surrounding him are many shelves and boxes with what appear to be wine and liquor bores. Directly behind the man is a box labeled "Fragile".

**Comprehension:** In the beginning, a bald man wearing tan pants, a black shirt, and a yellow vest appears to be taking boxes off a shelf on the left-side wall of a warehouse or brewery. In end, the man is seen facing away from the camera looking at the shelf he originally took the box from. The shelf appears to have tipped, as it's leaning sideways and its contents are all over the floor.

**GT Ans:** C **Baseline:** B ❌ | **+Perception:** B ❌ | **+Perception+Comprehension:** C ✅



# **Discussion: Open Problems**

# Visual Hallucinations

Can you fool LLMs?



Is there a **cat** in the image?  
[Easy Negative Instruction]



What color is the **cat** in the image?  
[Hard Negative Instruction]



Perception



Interpretation



Reasoning



# Spatial Reasoning

## Object Localization

Where is the dog from the camera's perspective?

- A. left.
- B. middle
- C. top
- D. right

 B. middle



## Positional & Relational Context

Where are the cows in from the man's perspective?

- A. behind
- B. left
- C. front
- D. right

 D. right

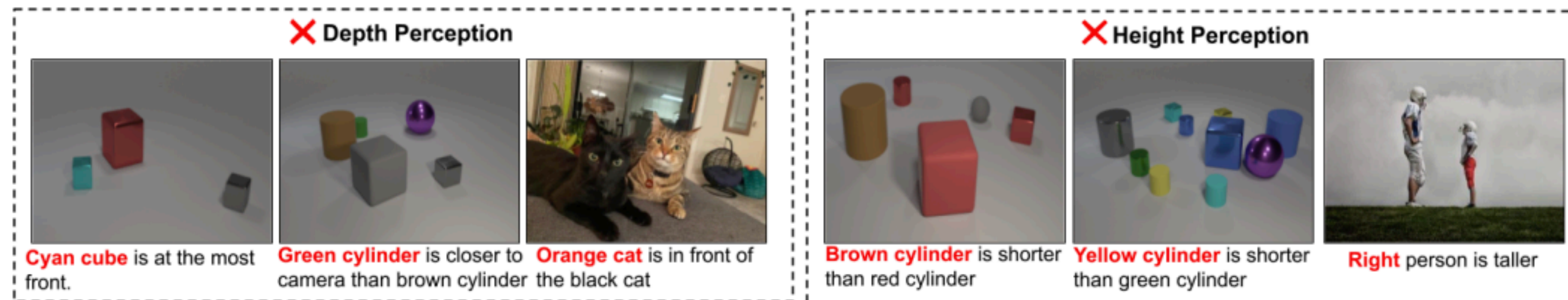


Figure 1: **Depth and height perception of existing VLM.** Here, we show GPT-4V failure to understand depth and height on existing synthetic (CLEVR [1]) dataset and real-world images taken from the internet.

 Perception

 Interpretation

 Reasoning



# Text != Image Description

- Most benchmarks test models' ability to describe the image
- But text isn't typically used to describe images, but rather **complement** them



The grass is always greener on the other side.



Perception



Interpretation



Reasoning



# Text != Image Description

- Most benchmarks test models' ability to describe the image
- But text isn't typically used to describe images, but rather **complement** them



Caption: A picture of a man with a hot dog in his mouth. ❌



The grass is always greener on the other side.



Perception



Interpretation



Reasoning



# Meme Interpretation

Me after reading that Elon Musk's Twitter is sinking fast, Meta lost \$700 billion, Amazon lost \$1 trillion and all cryptos are crashing



**Literal Meaning** (Image Caption):  
*Donald Duck is sleeping.*

**Metaphors** (Image + Text):  
*Donald Duck = meme poster*  
*Sleeping = being peaceful and not worried*

**Metaphorical Meaning** (Image + Text):  
*The meme poster is unbothered by discovering that Elon Musk's Twitter is sinking fast, Meta lost \$700 billion, Amazon lost \$1 trillion and all cryptos are crashing*

👁 Perception

💡 Interpretation

🤔 Reasoning



# (Visual) Commonsense is Culture-Dependent



Western weddings, more commonly present in datasets, can be very different from weddings in other parts of the world.

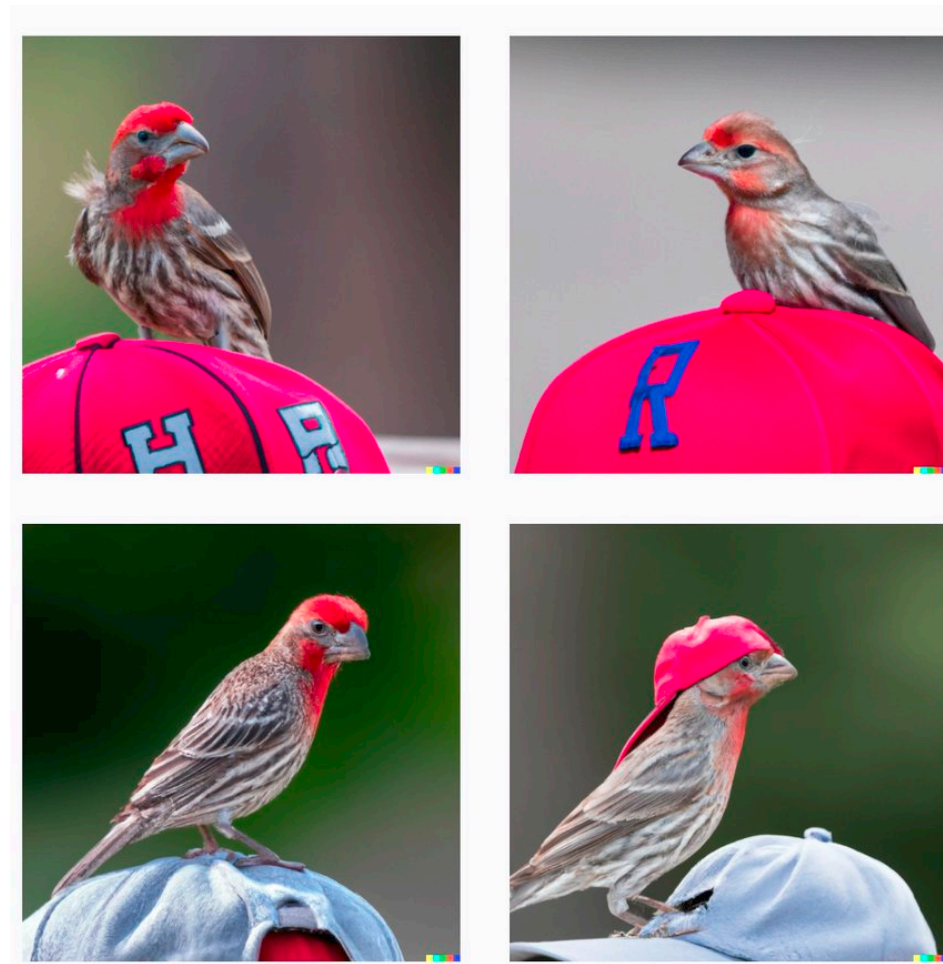
👁 Perception

💡 Interpretation

🤔 Reasoning



# Text-Image Generation



“A house finch wearing a baseball cap”



“A bat is flying over a baseball stadium”

“A spoon in a cup”



“A cup on a spoon”



👉 Understanding complex prompts

👁 Perception

💡 Interpretation

🧠 Reasoning

DALLE-2 is Seeing Double: Flaws in Word-to-Concept Mapping in Text2Image Models. Royi Rassin, Shauli Ravfogel, Yoav Goldberg. BlackboxNLP 2023.

A very preliminary analysis of DALL-E 2. Gary Marcus, Ernest Davis, Scott Aaronson. arXiv 2022.

Testing Relational Understanding in Text-Guided Image Generation. Colin Conwell and Tomer Ullman. arXiv 2022.



# Text to Image Biases

“A photo of a chef”



“A photo of a chef **in Africa**”



T2I models can generate **biased images** because the VL models (e.g. CLIP) can have these biased representations



Perception



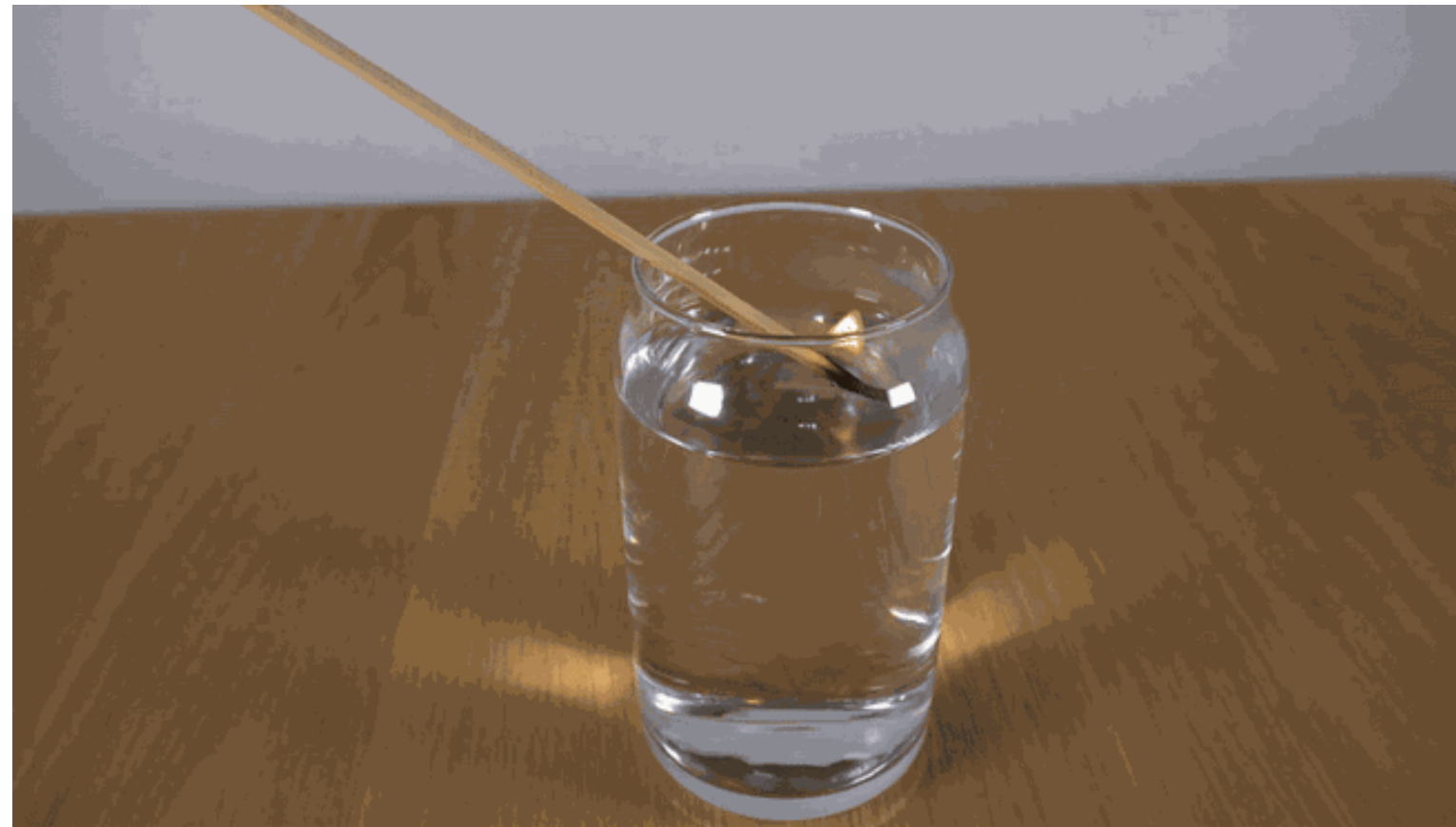
Interpretation



Reasoning



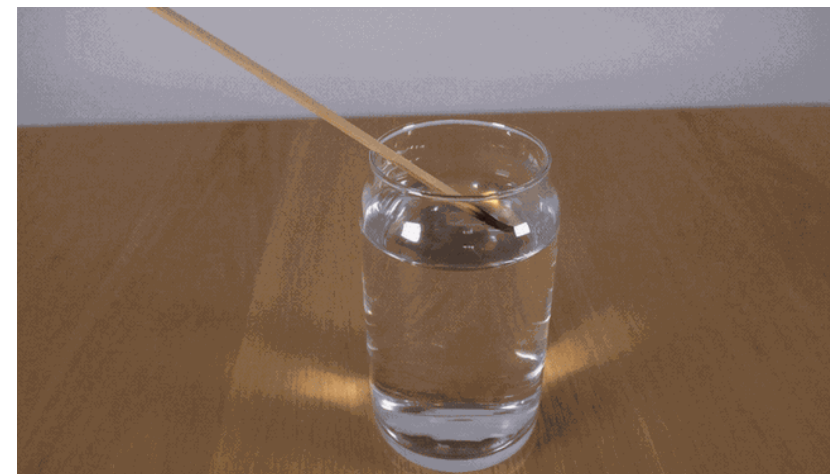
# Generative Models: Videos



VideoPoet (i2v)



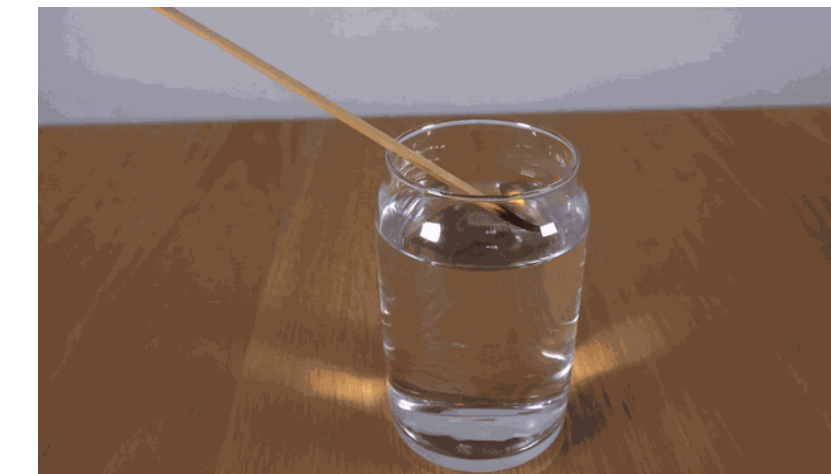
Sora (i2v)



Pika 1.0 (i2v)



Runway Gen 3 (i2v)



Every video generation model predicts that matchsticks can burn inside water

 Perception

 Interpretation

 Reasoning



# ARC-AGI Benchmark

Understanding complex patterns present on the grid (~600 problems)

EXAMPLES

Ex.1 Input (7x7)

Ex.1 Output (7x7)

Ex.2 Input (7x7)

Ex.2 Output (7x7)

TEST

Input (7x7)

Output (7x7)

1. Configure your output grid:

Copy from input

Reset

2. Click to select a color:

3. See if your output is correct:

Submit solution

François Chollet

@fchollet

Today OpenAI announced o3, its next-gen reasoning model. We've worked with OpenAI to test it on ARC-AGI, and we believe it represents a significant breakthrough in getting AI to adapt to novel tasks.

It scores 75.7% on the semi-private eval in low-compute mode (for \$20 per task in compute ) and 87.5% in high-compute mode (thousands of \$ per task). It's very expensive, but it's not just brute -- these capabilities are new territory and they demand serious scientific attention.

O SERIES PERFORMANCE / ARC-AGI SEMI-PRIVATE EVAL

100%

75%

50%

25%

0%

STEM GRAD

ARC-AGI-TUNED O3 HIGH 88%

AVG. MTURKER

76%

ARC-AGI-TUNED O3 LOW

KAGGLE SOTA

31%

32%

O1 LOW

O1 MED

O1 HIGH

13.33%

O1 PREVIEW

7.80%

O1-MINI

Semi-Private Score (%)

Cost Per Task

10:09 AM · Dec 20, 2024 · 2.1M Views

👁 Perception

💡 Interpretation

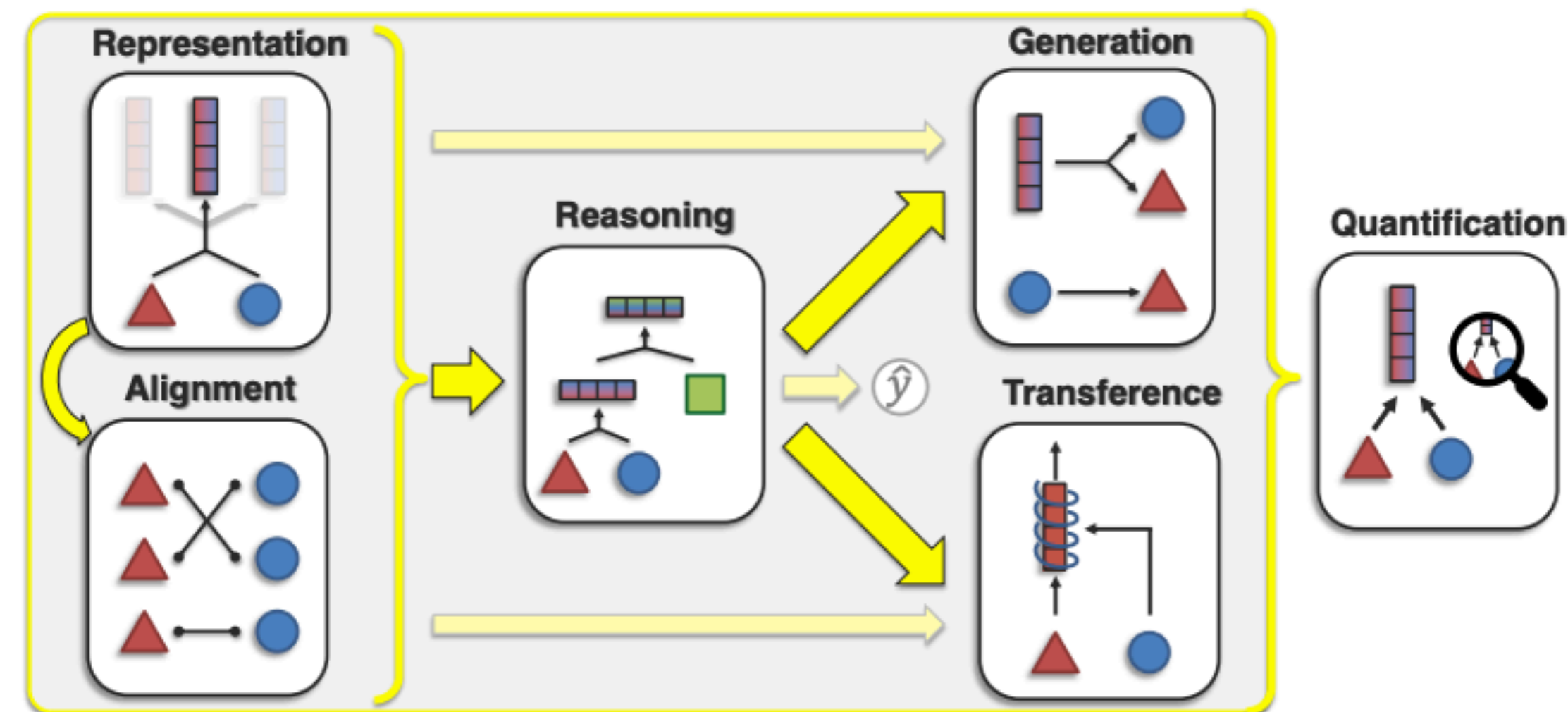
🤔 Reasoning

<https://arcprize.org/>

69

# More Open Problems...

- Agentic Frameworks
  - VLMs for task planning
- Long form video understanding
- Extending beyond VL: Aligning multiple modalities





**Thank You**